

# MATH 357 Honors Statistics

Yuyan Chen

January 2022

---

Lecture 1b

---

## 1 Chapter 1: Random Sampling

### 1.1 Basic Concepts

**Definition 1.1.** *The random variables (vectors)  $X_1, \dots, X_n$  are called a **random sample** if they are iid with some common distribution  $P$ .  $P$  is called the **population distribution** and  $n$  is called the **sample size**. **Data** are the observations (or realizations) of  $X_1, \dots, X_n$ , i.e.*

$$x_1, \dots, x_n.$$

Note: We regard  $P$  as **unknown**; it is a proxy for our lack of knowledge of some phenomenon. Our goal is to infer (learn)  $P$  or some of its properties from the basis of the observed data  $x_1, \dots, x_n$ .

**Example 1.2.**

Recall the definition of a random sample. This sampling model is also called sampling from an **infinite** population. Independence implies the distribution of  $X_2$  is unaffected by having sampled  $X_1 = x_1$ .

**Remark 1.3** (Finite population ( $N$ ) with  $P(\text{sampled}) = 1/N$ ).

1. *Sample with replacement*
2. *Sample without replacement:  $X_1, \dots, X_n$  are identically distributed but NOT independent. However when  $N$  is much larger than  $n$ , the independence assumption may be a good enough approximation.*

## 1.2 Descriptive Statistics

**Definition 1.4** (statistic). *Let  $X_1, \dots, X_n$  be a random sample from  $P$  on  $\mathbb{R}^d$ . Let  $T : \mathbb{R}^d \times \dots \times \mathbb{R}^d \rightarrow \mathbb{R}^h$  be a measurable mapping that does NOT depend on any unknown parameters. The random vector  $T(X_1, \dots, X_n)$  is called a **statistic**.*

Note that with Borel measure, all **continuous** functions are **measurable**.

**Example 1.5.**

$$\left(\frac{1}{n} \sum_{i=1}^n 1(X_i = 0) - p_0\right)^2$$

*is not a statistic since  $p_0$  is unknown.*

Rule of thumb: You must be able to evaluate a statistic. The observed value must be a scalar, not a term or formula.

**Definition 1.6.** *Let  $X_1, \dots, X_n$  be a random sample from  $P$  on  $\mathbb{R}$ . Then*

$$\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$$

is called the **sample mean** (a measure of central tendency). Furthermore,

$$S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$$

is called the **sample variance** (a measure of variability), and  $S$  is called the **sample standard deviation**. The observed values are denoted  $\bar{x}, s^2, s$ .

**Theorem 1.7.** For arbitrary  $x_1, \dots, x_n \in \mathbb{R}$ ,

(a)

$$\min_{a \in \mathbb{R}} \frac{1}{n} \sum_{i=1}^n (x_i - a)^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2.$$

(b)

$$(n-1)s^2 = \sum_{i=1}^n (x_i - \bar{x})^2 = \sum_{i=1}^n x_i^2 - n(\bar{x})^2$$

*Proof.*

$$\sum_{i=1}^n (x_i - a)^2 = \sum_{i=1}^n (x_i - \bar{x} + \bar{x} - a)^2$$

□

**Lemma 1.8.** Let  $X_1, \dots, X_n$  be a random sample from  $P$  on  $\mathbb{R}$ ,  $X \sim P$ ,  $g$  measurable so that  $E g(X)$  and  $\text{var } g(X)$  exist. Then

$$E \left( \sum_{i=1}^n g(X_i) \right) = n \cdot E(g(X))$$

$$\text{var} \left( \sum_{i=1}^n g(X_i) \right) = n \cdot \text{var}(g(X))$$

Note that

$$E(g(X)) = \int g(x)f(x)dx$$

**Theorem 1.9.** Let  $X_1, \dots, X_n$  be a random sample from  $P$  on  $\mathbb{R}$ ,  $X \sim P$ ,  $EX = \mu$  and  $\sigma^2 = \text{var } X$  are finite. Then,

$$(a) E\bar{X} = \mu$$

$$(b) \text{var}(\bar{X}) = \frac{\sigma^2}{n}$$

$$(c) E(S^2) = \sigma^2.$$

*Note: Theorem 1.9 holds for all  $P$  such that  $EX = \mu$  and  $\sigma^2 = \text{var} X$  are finite.*

**Example 1.10.**

**Definition 1.11** (order statistics). Let  $X_1, \dots, X_n$  be a random sample from  $P$  on  $\mathbb{R}$ . Placed in ascending order,

$$X_{(1)} \leq X_{(2)} \leq \dots \leq X_{(n)},$$

the ordered random variables are called the **order statistics**.  $X_{(r)}$  is called the  $r^{\text{th}}$  order statistic.

- $X_{(1)} \dots$  sample **minimum**
- $X_{(n)} \dots$  sample **maximum**
- $R = X_{(n)} - X_{(1)} \dots$  sample **range**
- $X_{med} \dots$  sample **median** (a measure of central tendency)

$$X_{med} = \begin{cases} X_{\frac{n+1}{2}}, & \text{if } n \text{ is odd} \\ \frac{X_{\frac{n}{2}} + X_{\frac{n}{2}+1}}{2}, & \text{if } n \text{ is even} \end{cases}$$

- sample  $(100 \cdot p)^{\text{th}}$  **percentile**, where  $p \in (\frac{1}{2n}, 1 - \frac{1}{2n})$  is:
  - $X_{(\{np\})}$  if  $p \in (\frac{1}{2n}, \frac{1}{2})$
  - $X_{med}$  if  $p = \frac{1}{2}$
  - $X_{(\{n+1-n(1-p)\})}$  if  $p \in (\frac{1}{2}, 1 - \frac{1}{2n})$

where  $b \in [0, \infty)$ ,  $\{b\}$  is the integer so that

$$j - \frac{1}{2} \leq b < j + \frac{1}{2}.$$

The definition of the  $(100 \cdot p)^{\text{th}}$  percentile is rigged so that if the  $(100 \cdot p)^{\text{th}}$  percentile is  $X_{(i)}$ , the  $i^{\text{th}}$  smallest observation, the  $(100 \cdot (1 - p))^{\text{th}}$  percentile is the  $i^{\text{th}}$  largest observation,  $X_{(n+1-i)}$ .

- the 25<sup>th</sup> percentiled is called the **first quartile** ( $Q_1$ )
- the 75<sup>th</sup> percentiled is called the **third quartile** ( $Q_3$ )
- their differntce  $IQR = Q_3 - Q_1$  (a measure of variability) is called **interqurtile range**.

**Lemma 1.12** (Mean absolute error). For any  $x_1, \dots, x_n \in \mathbb{R}$ , let  $X_{med}$  be the observed value of the sample median. Then for any  $a \in \mathbb{R}$ ,

$$\frac{1}{n} \sum_{i=1}^n |x_i - a| \geq \frac{1}{n} \sum_{i=1}^n |x_i - x_{med}|.$$

**Example 1.13.**

### Graphical data visualization

- Boxplot
- Histogram (for continuous data)

Partition the range  $[x_{(1)}, x_{(n)}]$  into  $k$  (chosen) bins.

$h_j$  is so that

$$\begin{aligned} h_j \cdot (b_{j+1} - b_j) &= \frac{1}{n} \sum_{i=1}^n 1(x_i \in [b_j, b_{j+1}]) \\ &\approx P(X \in [b_j, b_{j+1}]) \end{aligned}$$

The idea is that the histogram approximates the pdf of  $P$ .

- Bar chart/ bar plot (for discrete data) We observed  $k$  distinct value.

$$h_j = \frac{1}{n} \sum_{i=1}^n 1(x_i = b_j) \approx P(X = b_j)$$

Bar chart approximates the pmf of  $P$ .

### 1.3 Sampling distribution

**Definition 1.14** (sampling distribution). Consider a statistic  $T(X_1, \dots, X_n)$ . Its distribution is called the sampling distribution of  $T(X_1, \dots, X_n)$ .

**Theorem 1.15.** Consider a random sample from  $P$  on  $\mathbb{R}$ ,  $X \sim P$  and assume that  $X$  has a MGF (moment generating function)  $M_X$  on the interval  $I$ . Then  $\bar{X}$  has MGF

$$M_{\bar{X}}(t) = (M_X(t/n))^n$$

**Example 1.16.**

- $X \sim \mathcal{N}(\mu, \sigma^2)$ ,  $\bar{X} \sim \mathcal{N}(\mu, \sigma^2/n)$
- $X \sim \text{Bin}(m, p)$ ,  $n \cdot \bar{X} \sim \text{Bin}(m \cdot n, p)$
- $X \sim \text{Gamma}(\alpha, \beta)$ ,  $\bar{X} \sim \text{Gamma}(\alpha \cdot n, \beta/n)$ .

Observation: the sampling distribution of  $T(X_1, \dots, X_n)$  **depends** on the population distribution  $P$ .

**Theorem 1.17.** Let  $X_1, \dots, X_n$  be a random sample from  $P$  on  $\mathbb{R}$ . Then from any  $x \in \mathbb{R}$ ,  $r \in \{1, \dots, n\}$ ,

$$P(X_{(r)} \leq x) = F_{X_{(r)}}(x) = \sum_{k=r}^n \binom{n}{k} \{F(x)\}^k \{1 - F(x)\}^{n-k}$$

*Proof.* Fix  $x \in \mathbb{R}$ ,  $r \in \{1, \dots, n\}$ . Let

$$\begin{aligned} Y &= \#i : X_i \leq x \\ &= \sum_{i=1}^n 1(X_i \leq x), \text{ iid Bernoulli}(F(x)), \text{ since } P(X_i \leq x) = F(x) \end{aligned}$$

Hence,  $Y \sim \text{Bin}(n, F(x))$ .

$$\begin{aligned} P(X_{(r)} \leq x) &= P(Y \geq r) \\ &= \sum_{k=r}^n \binom{n}{k} (F(x))^k (1 - F(x))^{n-k} \end{aligned}$$

□

Note: if  $P$  has a pdf  $f$ , then  $X_{(r)}$  has a pdf

$$f_{(X_{(r)})}(x) = \frac{n!}{(r-1)!(n-r)!} \{F(x)\}^{r-1} f(x) \{1 - F(x)\}^{n-r}.$$

**Example 1.18.** Suppose  $U_1, \dots, U_n$  from  $U(0, 1)$ . Then  $U_{(r)}$  has a pdf

$$f_{U_{(r)}}(u) = \frac{n!}{(r-1)!(n-r)!} u^{r-1} (1-u)^{n-r}.$$

Note that  $\Gamma(n) = (n-1)!$ . Hence,  $U_{(r)} \sim \text{Beta}(r, n-r+1)$ . In particular,

$$E(U_{(r)}) = \frac{r}{n+1}.$$

Note: for  $\mathcal{U}(a, b)$ ,  $f(x) = 1/(b-a)$  for  $x \in [a, b]$ , 0 otherwise.



## 1.4 Sampling from the Normal Population

Throughout this section,  $X \sim \mathcal{N}(\mu, \sigma^2)$ , where  $\mu$  and  $\sigma^2$  are unknown.

**Theorem 1.19.** *Let  $X_1, \dots, X_n$  be a random sample from  $\mathcal{N}(\mu, \sigma^2)$ . Let  $\bar{X}$  and  $S^2$  be the sample mean and variance. Then,*

(a)

$$\bar{X} \sim \mathcal{N}\left(\mu, \frac{\sigma^2}{n}\right)$$

(b)  $\bar{X}$  and  $S^2$  are independent.

*Proof.* (b) Let  $X_i^*$  be the standardized variable such that

$$X_i^* = \frac{X_i - \mu}{\sigma}.$$

Then,  $X_i^* \sim \mathcal{N}(0, 1)$ . We have

$$\begin{aligned} \bar{X}^* &= \frac{\bar{X} - \mu}{\sigma} \\ (S^*)^2 &= \frac{S^2}{\sigma^2}. \end{aligned}$$

Both are one-to-one function to  $\bar{X}$  and  $S^2$ , respectively. Hence, WLOG, we can assume  $\mu = 0$  and  $\sigma^2 = 1$  and if  $\bar{X}^* \perp (S^*)^2$ ,  $\bar{X} \perp S^2$ . Note that

$$S^2 = \frac{1}{n-1} \left( \underbrace{\left(-\sum_{i=2}^n (X_i - \bar{X})\right)^2}_{=X_1 - \bar{X}} + \sum_{i=2}^n (X_i - \bar{X})^2 \right).$$

**Lemma 1.20.**  $X_2, \dots, X_n$  iid  $\mathcal{N}(0, 1)$ . Then,

$$\bar{X} \perp (X_2 - \bar{X}, \dots, X_n - \bar{X}).$$

*Proof.* Define  $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$  as

$$(x_1, \dots, x_n) \rightarrow (\bar{x}, x_2 - \bar{x}, \dots, x_n - \bar{x}).$$

Then,  $T^{-1} : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is

$$(y_1, \dots, y_n) \rightarrow \left( \underbrace{y_1 - \sum_{i=2}^n y_i}_{=n \cdot y_1 - \sum_{i=2}^n (y_i + y_1)}, y_2 + y_1, \dots, y_n + y_1 \right).$$

Jacobi matrix  $|J| = n$ .

$$\begin{aligned} f_{(Y_1, \dots, Y_n)}(y_1, \dots, y_n) &= f_{(X_1, \dots, X_n)}(T^{-1}(y_1, \dots, y_n)) \cdot |J| \\ &= \left( \left( \frac{1}{\sqrt{2\pi}} \right)^n \exp\left(-\frac{1}{2} \left( (y_1 - \sum_{i=2}^n y_i)^2 + \sum_{i=2}^n (y_i + y_1)^2 \right) \right) \right) \cdot n \\ &= \sqrt{n} \left( \frac{1}{\sqrt{2\pi}} \right) \exp\left(-\frac{1}{2} (n y_1^2)\right) \\ &\quad \cdot \sqrt{n} \left( \frac{1}{\sqrt{2\pi}} \right)^{n-1} \exp\left(-\frac{1}{2} \left( \left( \sum_{i=2}^n y_i \right)^2 + \sum_{i=2}^n y_i^2 \right) \right) \\ &= f_1(y_1) \cdot f_2(y_2, \dots, y_n) \end{aligned}$$

**Theorem 12.7** (from Jacod & Protter) Let  $X = (X_1, \dots, X_n)$  have joint density  $f$ . Let  $g : \mathbb{R}^n \rightarrow \mathbb{R}^n$  be continuously differentiable and injective, with non-vanishing Jacobian. Then  $Y = g(X)$  has density

$$f_Y(y) = \begin{cases} f_X(g^{-1}(y)) |\det J_{g^{-1}}(y)|, & \text{if } y \text{ is in the range of } g \\ 0, & \text{otherwise.} \end{cases}$$

□

Since  $S^2$  is a function of  $(X_2 - \bar{X}, \dots, X_n - \bar{X})$  which we now know is independent of  $\bar{X}$ . □

**Definition 1.21** (Chi-squared distribution). The  $\chi_\nu^2$  distribution has a pdf given, for all  $x > 0$ ,

$$f(x; \nu) = \frac{1}{2^{\nu/2} \Gamma(\frac{\nu}{2})} \cdot x^{\nu/2-1} \cdot e^{-x/2}$$

and 0 otherwise. The  $\chi_\nu^2$  distribution is in fact the  $\text{Gamma}(\frac{\nu}{2}, 2)$ . The MGF of  $\chi_\nu^2$  is given, for all  $t < \frac{1}{2}$ , by  $M_{\chi_\nu^2} = (1 - 2t)^{-\nu/2}$ .

**Lemma 1.22.**

- (a) When  $X \sim \chi_\nu^2$ , then  $EX = \nu$  and  $\text{var } X = 2\nu$
- (b)  $X_1 \sim \chi_{\nu_1}^2$ ,  $X_2 \sim \chi_{\nu_2}^2$ , and  $X_2 \perp X_1$ , then  $X_1 + X_2 \sim \chi_{\nu_1+\nu_2}^2$
- (c)  $X \sim \mathcal{N}(0, 1)$  then  $X^2 \sim \chi_1^2$ .

**Theorem 1.23.** Supposet that  $X_1, \dots, X_n$  is a random sample from  $\mathcal{N}(\mu, \sigma^2)$ . Then,

$$\frac{(n-1)S^2}{\sigma^2} \sim \chi_{n-1}^2.$$

Motivation for t distribution: Consider

$$\sqrt{n} \frac{\bar{X} - \mu}{\sigma} \sim \mathcal{N}(0, 1),$$

where  $\sigma$  is unknown. Instead:

$$\sqrt{n} \frac{\bar{X} - \mu}{S} \equiv T.$$

Note that  $T$  is a statistic.

**Definition 1.24** (Student t distribution). *The Student t distribution with  $\nu$  degrees of freedom,  $t_\nu$ , has pdf*

$$f(x; \nu) = \frac{\Gamma(\frac{\nu+1}{2})}{\sqrt{\nu\pi} \cdot \Gamma(\frac{\nu}{2})} \left(1 + \frac{x^2}{\nu}\right)^{-\frac{\nu+1}{2}}, \quad x \in \mathbb{R}.$$

**Lemma 1.25.** *Let  $X \sim t_\nu$ . The the following holds:*

- (a)  $EX = 0$  if  $\nu > 1$ . If  $\nu \leq 1$ ,  $EX$  does not exist. Note:  $t_1$  is Cauchy(1).
- (b)  $\text{var}X = \frac{\nu}{\nu-2}$  if  $\nu > 2$ . If  $\nu \leq 2$ , then  $\text{var}X$  does not exist.
- (c)

$$X \stackrel{d}{=} \frac{Z}{\sqrt{V/\nu}}$$

where  $Z \sim \mathcal{N}(0, 1)$ ,  $V \sim \chi_\nu^2$ , and  $Z \perp V$ .

**Theorem 1.26.** *Suppose that  $X_1, \dots, X_n$  is a random sample from  $\mathcal{N}(\mu, \sigma^2)$ . Then,*

$$T = \sqrt{n} \cdot \frac{\bar{X} - \mu}{S} \sim t_{n-1}$$

*Proof.* Lemma 1.25 (c). □

**Definition 1.27.** *The Fisher-Snedecor  $F_{\nu_1, \nu_2}$  with  $\nu_1$  and  $\nu_2$  dof is the distribution of*

$$\frac{V_1/\nu_1}{V_2/\nu_2}$$

where  $V_1 \sim \chi_{\nu_1}^2$ ,  $V_2 \sim \chi_{\nu_2}^2$ ,  $V_1 \perp V_2$ .

**Theorem 1.28.** Let  $X_1, \dots, X_n$  be a random sample from  $\mathcal{N}(\mu_1, \sigma_1^2)$ . Let  $Y_1, \dots, Y_m$  be a random sample from  $\mathcal{N}(\mu_2, \sigma_2^2)$ . Suppose that  $(X_1, \dots, X_n)$  and  $(Y_1, \dots, Y_m)$  are independent; let  $S_X^2$  and  $S_Y^2$  be their respective sample variances, then

$$\underbrace{\frac{S_X^2/\sigma_1^2}{S_Y^2/\sigma_2^2}}_{\text{not a statistic since } \sigma_1^2 \text{ and } \sigma_2^2 \text{ unknown}} \sim F_{n-1, m-1}.$$

Remark: Theorem 1.28 will serve as later to derive the so-called F test. Imagine we want to assess whether  $\sigma_1^2 = \sigma_2^2$ .

$$\underbrace{\frac{S_X^2}{S_Y^2}}_{\text{is a statistic}} \neq 1 \sim F_{n-1, m-1}.$$

## 2 Chapter 2: Theory of point estimation

### 2.1 Parametric model

Throughout this chapter, we will assume that  $X_1, \dots, X_n$  is a random sample from  $P$  and that

$$P \in \mathcal{P} = \{P_\theta, \theta \in \Theta\}.$$

- $\mathcal{P}$  is called a **parametric model** for  $P$ .
- $\theta$  is called a **parameter**.
- $\Theta$  is called a **parameter space** and we assume that  $\Theta \in \mathbb{R}^k$ .

We will denote the CDF of  $P_\theta$  by  $F_\theta$  and its pdf/pmf by  $f(x; \theta)$ ,  $x \in \mathbb{R}$ .

**Example 2.1.** For Newcomb's measurements, we may assume

$$\mathcal{P} = \left\{ \underbrace{\mathcal{N}(\mu, \sigma^2)}_{P_\theta}, \underbrace{(\mu, \sigma^2)}_{\theta} \in \underbrace{\mathbb{R} \times (0, \infty)}_{\Theta} \right\}$$

Note: A parametric model for  $P$  is an **assumption**. It is always an **approximation** to the reality which may or may NOT be true. Our goal is to estimate the unknown parameter  $\theta$  from the observed data  $x_1, \dots, x_n$ .

**Definition 2.2.** A **point estimator** is any statistic  $W(X_1, \dots, X_n)$  which has been constructed with the aim to estimate  $\theta$ . The observed value of  $W$ , i.e.  $W(x_1, \dots, x_n)$  is called the **estimate** of  $\theta$ .

Note: we do NOT require that the range of  $W$  is  $\Theta$ .

Notation: estimators are often denoted  $\hat{\theta}$ ,  $\hat{\theta}(X_1, \dots, X_n)$ ,  $\tilde{\theta}$ , and  $\theta_n$ .

## 2.2 Methods of finding estimators

Recall: an estimator is a statistic  $W(X_1, \dots, X_n)$ .

### 2.2.1 Method of moments

sample moment:

$$m_j = \frac{1}{n} \sum_{i=1}^n X_i^j.$$

From Theorem 1.9, we know that if  $EX^j < \infty$ ,  $E(m_j) = EX^j$ . If  $E(X^j)^2 < \infty$ , then from the weak law of large numbers,

$$m_j \xrightarrow{P} EX^j \text{ as } n \rightarrow \infty$$

Now suppose  $\theta = (\theta_1, \dots, \theta_k)$ . The method of moments proceeds as follows:

1. Calculate  $k$  moments of  $P_\theta$  (population moments), i.e:

$$EX^j = \mu_j(\theta), \quad j = 1, \dots, k.$$

2. Calculate the  $j^{\text{th}}$  sample moment

$$m_j = \frac{1}{n} \sum_{i=1}^n X_i^j, \quad j = 1, \dots, k.$$

3. Equate

$$m_j = \mu_j(\theta), \quad j = 1, \dots, k.$$

If there is a unique solution, it is called a **method of moments estimator** of  $\theta$ .

- “easy”

- usually consistent since

$$Y \xrightarrow{P} y \implies f(Y_n) \xrightarrow{P} f(Y)$$

- usually biased (e.g. Jensen inequality)

Remark You may need to choose moments other than the first  $k$ , depending on the distribution  $P_\theta$ .

**Example 2.3.** Suppose  $X_1, \dots, X_n$  is a random sample from the Normal distribution, i.e:

$$P \in \{\mathcal{N}(\mu, \sigma^2), (\mu, \sigma^2) \in \mathbb{R} \times (0, \infty)\}.$$

The method-of-moment estimator of  $(\mu, \sigma^2)$  is

$$\left( \bar{X}, \underbrace{\frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2}_{\frac{n-1}{n} S^2} \right).$$

**Example 2.4.** Consider a random sample  $X_1, \dots, X_n$  from  $\text{Bin}(N, p)$ , i.e.

$$P \in \{\text{Bin}(N, p), p \in (0, 1)\}$$

where  $N$  is known. The method of moment generator of  $p$  is

$$\hat{p} = \frac{1}{N} \bar{X}.$$

If  $N$  is unknown, the method-of-moment estimator of  $(p, N)$  is

$$\left( \frac{\bar{X} - \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2}{\bar{X}}, \frac{(\bar{X})^2}{\bar{X} - \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2} \right).$$

Note: the method of moment estimators above may well be negative. The estimator of  $N$  may not be an integer.



**Example 2.5.** Consider a random sample from  $U(-\theta, \theta)$ ,

$$P \in \{U(-\theta, \theta), \theta \in (0, \infty)\}.$$

We have

$$EX = \frac{-\theta + \theta}{2} = 0,$$

which is not useful. Use the second moment, we obtain

$$\hat{\theta} = \sqrt{\frac{1}{2n} \sum_{i=1}^n X_i^2}.$$

Consider  $x_0 = 0, x_1 = 1 \sim U(\theta, \theta)$ . We find  $\theta$  to be

$$\hat{\theta} = \sqrt{\frac{1}{4}(0+1)} = \frac{1}{2}.$$

However,  $0, 1 \notin (-\frac{1}{2}, \frac{1}{2})$ .

### 2.2.2 Method of Maximum Likelihood

Assume  $X_1, \dots, X_n$  is a random sample from

$$P \in \{P_\theta, \theta \in \Theta\}.$$

Assume also that for each  $\theta \in \Theta$ ,  $P_\theta$  has a PMF/PDF.

**Definition 2.6.** Given the observed data  $x_1, \dots, x_n$ , the function of  $\theta$  defined by

$$L(\theta) = L(\theta; x_1, \dots, x_n) = \prod_{i=1}^n f(x_i; \theta)$$

is called the *likelihood function*.

Note that the likelihood function is a function of  $\theta$  for a fixed set  $x_1, \dots, x_n$ .

#### Example 2.7.

##### Interpretation of the likelihood function

- If  $P_\theta$  is discrete, then the value of  $L$  at  $\theta_0$  is

$$\begin{aligned} L(\theta_0) &= P_{\theta_0}(X_1 = x_1, \dots, X_n = x_n) \\ &= L(\theta_0; x_1, \dots, x_n) \end{aligned}$$

$L(\theta_0)$  is the probability of observing the data we observed if the parameter  $\theta = \theta_0$ . For example, in Example 2.7,

$$L(1) = 3.8 \times 10^{-5}$$

is the probability (or “likelihood”) of observing 1,2,2,5 when  $\lambda = 1$ .

- When  $P_\theta$  is continuous, this interpretation is still used, but in an approximation sense. Because  $P(X_1 = x_1, \dots, X_n = x_n) = 0$ , we need to consider

$$\begin{aligned}
& P(X_1 \in (x_1 - \varepsilon, x_1 + \varepsilon), \dots, X_n \in (x_n - \varepsilon, x_n + \varepsilon)) \\
&= \int_{x_1 - \varepsilon}^{x_1 + \varepsilon} \cdots \int_{x_n - \varepsilon}^{x_n + \varepsilon} \prod_{i=1}^n f(t_i; \theta) dt_n \cdots dt_1 \\
&\approx \prod_{i=1}^n f(t_i; \theta) \cdot (2\varepsilon)^n \\
&= L(\theta; x_1, \dots, x_n) \cdot \underbrace{(2\varepsilon)^n}_{\text{does not contain } \theta}
\end{aligned}$$

provided that  $\varepsilon > 0$  is very small. So,

$$L(\theta; x_1, \dots, x_n) \propto P(X_1 \in (x_1 - \varepsilon, x_1 + \varepsilon), \dots, X_n \in (x_n - \varepsilon, x_n + \varepsilon))$$

Whether  $P_\theta$  is continuous or discrete, we can say that if

$$L(\theta_1; x_1, \dots, x_n) \geq L(\theta; x_1, \dots, x_n),$$

it is more “likely” to have observed  $x_1, \dots, x_n$  when  $\theta = \theta_1$  than  $\theta = \theta_2$ .

**Definition 2.8.** For an observed sample  $x_1, \dots, x_n$ , the **maximum likelihood (ML) estimate** of  $\theta$ , denoted  $\hat{\theta}(x_1, \dots, x_n)$  is a value such that

$$L(\hat{\theta}(x); x_1, \dots, x_n) = \sup_{\theta \in \Theta} L(\theta; x_1, \dots, x_n)$$

provided it exists. If the ML estimate exists for almost all samples  $x_1, \dots, x_n$  and if the mapping  $\hat{\theta} : \mathbb{R}^n \rightarrow \mathbb{R}^h$

$$(x_1, \dots, x_n) \rightarrow \hat{\theta}(x_1, \dots, x_n)$$

is measurable,  $\hat{\theta}(X_1, \dots, X_n)$  is called the ML estimator of  $\theta$ .

“Almost all samples” means that  $\hat{\theta}(\underline{x})$  exists for all  $\underline{x} \in A$  when

$$P_{\theta}((X_1, \dots, X_n) \in A) = 1$$

for all  $\theta \in \Theta$ .

In Definition 2.8, note that the ML estimate is the value  $\hat{\theta}(\underline{x})$  in  $\Theta$  at which the sup is attained.

The **log-likelihood function** is defined as

$$l(\theta; \underline{x}) = \log L(\theta; \underline{x}) = \sum_{i=1}^n \log f(x_i; \theta).$$

Typically,  $l$  is smooth and we can look for its maximum by calculating

$$\frac{\partial l}{\partial \theta_j}(\theta; x_1, \dots, x_n) = 0, \quad j = 1, \dots, k$$

and inspect the solutions.

**Example 2.9.** Consider a random sample from a Binomial population with KNOWN size  $N$ :

$$P \in \{Bin(N, p), p \in [0, 1]\}.$$

The likelihood function is

$$L(p; x_1, \dots, x_n) = \prod_{i=1}^n \binom{N}{x_i} p^{x_i} (1-p)^{N-x_i}.$$

The ML estimator is thus  $\hat{p} = \frac{\bar{X}}{N}$  (and the same as the method-of-moment estimator.)

Careful: If we choose

$$\{Bin(N, p), p \in (0, 1)\}$$

then ML estimate does not exist when  $\bar{x} = 0$  or  $\bar{x} = N$ . Since  $P_p(\bar{X} = 0) \neq 0$ ,  $P_p(\bar{X} = N) \neq 0$ , the ML estimator does not exist in this case.

**Example 2.10.** Consider a random sample from

$$P \in \{\mathcal{N}(\mu, 1), \mu \in \mathbb{R}\}.$$

ML estimator of  $\mu$  is  $\hat{\mu} = \bar{X}$ . Suppose now we know that  $\mu \geq 0$ . In this case,  $\bar{x}$  is not the ML estimate when  $\bar{x} < 0$ . Note that

$$\frac{\partial l}{\partial \mu} = n \cdot (\bar{x} - \mu) < 0$$

if  $\bar{x} < \mu$ . Hence,  $l$  is decreasing on  $[0, \infty)$ . Hence,  $l$  is maximized at  $\tilde{\mu}(\underline{x}) = 0$ . In this (constrained) estimation problem, the MLE is

$$\tilde{\mu} = \max(\bar{X}, 0).$$

**Example 2.11.** Take a random sample from  $P \in \{U(0, \theta), \theta \in (0, \infty)\}$ . To calculate the MLE,

$$\begin{aligned} L(\theta; \underline{x}) &= \prod_{i=1}^n \frac{1}{\theta} \cdot 1(x_i \in [0, \theta]) \\ &= \left(\frac{1}{\theta}\right)^n \cdot 1\left(\min_{1 \leq i \leq n} x_i \geq 0\right) \cdot 1\left(\max_{1 \leq i \leq n} x_i \leq \theta\right). \end{aligned}$$

The MLE is

$$\tilde{\theta}(\underline{x}) = \max_{1 \leq i \leq n} x_i.$$

Note: if the density function has a compact support, use the **indicator function** to denote the support.

**Theorem 2.12** (Invariance Principle of the MLE). Consider a statistical model  $\{P_\theta, \theta \in \Theta\}$  and suppose that  $g : \Theta \rightarrow \mathbb{R}^m$  is an arbitrary measurable function. Set  $\Gamma = g(\Theta)$  to be the range of  $g$  and suppose we wish to estimate  $\gamma = g(\theta)$ . Then if  $\tilde{\theta}(\underline{x})$  is the MLE of  $\theta$ ,

$$\hat{\gamma} = g(\tilde{\theta}(\underline{x}))$$

is the MLE of  $\gamma$  in the following sense: for

$$L^*(\gamma; \underline{x}) = \sup_{\theta \in \Theta: g(\theta) = \gamma} L(\theta; \underline{x})$$

then

$$L^*(\hat{\gamma}; \underline{x}) = \sup_{\gamma \in \Gamma} L^*(\gamma; \underline{x})$$

*Proof.* WTS:  $L^*(\hat{\gamma}; \underline{x}) = \sup_{\gamma \in \Gamma} L^*(\gamma; \underline{x})$ .

$$\begin{aligned} L^*(\hat{\gamma}; \underline{x}) &= \sup_{\theta \in \Theta: g(\theta) = \hat{\gamma}} L(\theta; \underline{x}) \\ &= L(\hat{\theta}; \underline{x}) \\ &= \sup_{\theta \in \Theta} L(\theta; \underline{x}) \\ &= \sup_{\gamma \in \Gamma} \sup_{\theta \in \Theta: g(\theta) = \gamma} L(\theta; \underline{x}) \\ &= \sup_{\gamma \in \Gamma} L^*(\gamma; \underline{x}) \end{aligned}$$

□

**Example 2.13.**

- $\{Bin(N, p), p \in [0, 1]\}$ ,  $N$  is known.
- $\{Exponential(\lambda), \lambda > 0\}$ . The MLE of  $\lambda$  is  $\bar{X}$ .

**Example 2.14.**

- $\{\mathcal{N}(\mu, \sigma^2), \mu \in \mathbb{R}, \sigma^2 > 0\}$ . The MLE of  $(\mu, \sigma^2)$  is  $(\bar{X}, \frac{n-1}{n}S^2)$ .

In the Bayesian approach, our uncertainty (lack of knowledge) of  $\theta$  is expressed by a probability density  $\pi(\theta)$ , called the **prior**. Once we have collected the data, we will update the prior by incorporating the information from the data. This leads to the so-called **posterior density**. Bayesian estimation tends to perform better for small sample size.

Assume for simplicity that  $\theta$  is univariate and let  $\pi$  be the pmf/pdf of the prior distribution (i.e. a distribution on  $\Theta$  of your choice). Suppose the density (pmf/pdf) of  $(X_1, \dots, X_n)$  given  $\theta$

$$\prod_{i=1}^n f(x_i; \theta).$$

The posterior density is the conditional density of  $\theta$  given the observed data (i.e. conditionally on  $X_1 = x_1, \dots, X_n = x_n$ ). The posterior density is given by

$$\pi(\theta|x_1, \dots, x_n) = \frac{\prod_{i=1}^n f(x_i; \theta)}{m(x_1, \dots, x_n)} \cdot \pi(\theta)$$

where

$$m(x_1, \dots, x_n) = \int_{\Theta} \prod_{i=1}^n f(x_i; \theta) \pi(\theta) d\theta$$

is the marginal density of  $X_1, \dots, X_n$  (unconditional). A Bayesian estimate of  $\theta$  could be the mean of the posterior distribution with density (pmf/pdf)  $\pi(\theta|x_1, \dots, x_n)$ .

**Example 2.15.**  $X_1, \dots, X_n$  a Bernoulli random sample,  $X_i \sim \text{Bernoulli}(p)$ .  $\Theta(0, 1)$ . The prior density is **chosen** to be  $\text{Beta}(\alpha, \beta)$ . The Bayesian estimate  $p_B$  as the expected value of the posterior:

$$p_B = \frac{n\bar{x} + \alpha}{n + \alpha + \beta} = \frac{n}{n + \alpha + \beta} \cdot \underbrace{\bar{x}}_{\text{sample mean}} + \frac{\alpha + \beta}{n + \alpha + \beta} \cdot \underbrace{\frac{\alpha}{\alpha + \beta}}_{\text{expectation of the prior}}$$

Trick to avoid integration:

$$\pi(\theta|x_1, \dots, x_n) = \underbrace{c(x_1, \dots, x_n)}_{\text{normalizing constant}} \cdot \underbrace{\prod_{i=1}^n f(x_i; \theta)}_{\text{likelihood}} \cdot \underbrace{\pi(\theta)}_{\text{prior}}$$

$\propto$  likelihood  $\times$  prior

**Example 2.16.**  $X_1, \dots, X_n$  a random sample from  $\text{Exponential}(\lambda)$ . The parameter space is  $(0, \infty)$ .

- Likelihood is  $\lambda^n e^{-n\bar{x}\lambda}$
- Prior:  $\text{Gamma}(\alpha, \beta)$

$$\pi(\lambda) = \frac{\beta^\alpha}{\Gamma(\alpha)} \lambda^{\alpha-1} e^{-\lambda\beta}, \quad \lambda > 0$$

- Posterior:  $\text{Gamma}(n + \alpha, n\bar{x} + \beta)$
- Bayesian estimator of  $\lambda$ :

$$\hat{\lambda}_B = \frac{n + \alpha}{n\bar{x} + \beta} \xrightarrow{n \rightarrow \infty} \frac{1}{\bar{x}}$$



## 2.3 Method of evaluating estimators

**Definition 2.17.** Consider a statistical model

$$P = \{P_\theta, \theta \in \Theta\}$$

and  $\gamma : \Theta \rightarrow \mathbb{R}^m$ . Let  $T(X_1, \dots, X_n)$  be an estimator of  $\gamma(\theta)$ . Then:

(a)  $T$  is called **unbiased** if  $\forall \theta \in \Theta$ ,

$$E_\theta T(X_1, \dots, X_n) = \gamma(\theta).$$

The difference  $E_\theta T(X_1, \dots, X_n) - \gamma(\theta)$  is called the **bias** of  $T$ , and denoted  $\text{bias}_\theta(T)$ .

(b) If for all  $\theta \in \Theta$ ,

$$\lim_{n \rightarrow \infty} E_\theta T(X_1, \dots, X_n) = \gamma(\theta),$$

then  $T$  is called **asymptotically unbiased**.

(c) (Weak consistency)  $T$  is called **consistent** if for all  $\theta \in \Theta$

$$T(X_1, \dots, X_n) \xrightarrow{P_\theta} \gamma(\theta)$$

as  $n \rightarrow \infty$ .

(d) The **mean square error** of  $T$  is

$$MSE_\theta = E_\theta \{T(X_1, \dots, X_n) - \gamma(\theta)\}^2.$$

Note: the expectation, variance, etc. of  $T$  is taken w.r.t.  $P_\theta$  and hence **depends** on  $\theta$ . For all  $\theta \in \Theta$ :

$$\begin{aligned} MSE_\theta T &= E_\theta(T - \gamma(\theta))^2 \\ &= E_\theta(T - E_\theta T + E_\theta T - \gamma(\theta))^2 \\ &= E_\theta(T - E_\theta T)^2 + (E_\theta T - \gamma(\theta))^2 + 2(E_\theta T - \gamma(\theta)) \cdot E_\theta(T - E_\theta T) \\ &= var_\theta T + (bias_\theta T)^2 \end{aligned}$$

**Example 2.18.** Consider a random sample  $X_1, \dots, X_n$  from  $\mathcal{N}(\mu, \sigma^2)$ . We know from Theorem 1.9 that  $E\bar{X} = \mu$ ,  $ES^2 = \sigma^2$ .

$$\begin{aligned} MSE(\bar{X}) &= var\bar{X} = \frac{\sigma^2}{n} \\ MSE(S^2) &= varS^2 = \frac{2\sigma^2}{n-1}. \end{aligned}$$

The MLE of  $\sigma^2$  is

$$\hat{\sigma}^2 = \frac{n-1}{n} S^2.$$

and

$$bias(\hat{\sigma}^2) = -\frac{1}{n}\sigma^2.$$

Hence,  $\hat{\sigma}^2$  is asymptotically unbiased.

$$\begin{aligned} MSE(\hat{\sigma}^2) &= var(\hat{\sigma}^2) + (bias(\hat{\sigma}^2))^2 \\ &= \underbrace{\frac{2\sigma^4}{n-1}}_{MSE(S^2)} \cdot \underbrace{\frac{2n^2 - 3n + 1}{2n^2}}_{\leq 1} \\ &\leq MSE(S^2) \end{aligned}$$

Trade-off between the bias and the variance

- Increasing the  $(bias)^2$  led to a **decrease** of the variance and an overall decrease of the MSE.

- The MSE is just a criterion, meaning that we should not discard  $S^2$  based on the MSE alone.

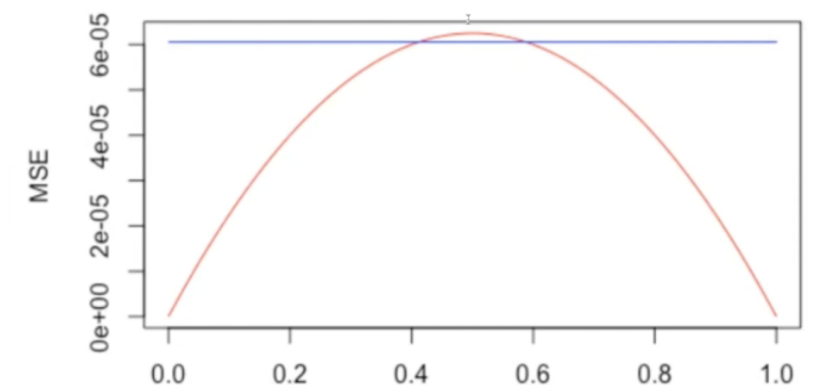
**Example 2.19.** The Bayesian estimator of  $p$  is

$$\hat{p}_B = \frac{n\bar{X} + \alpha}{n + \alpha + \beta}.$$

Clearly,  $\hat{p}_B$  is biased.

$$MSE\hat{p}_B = \frac{\alpha^2 + p(n - 2\alpha^2 - 2\alpha\beta) + p^2(-n + \alpha^2 + \beta^2 + 2\alpha\beta)}{(n + \alpha + \beta)^2}.$$

We can decide to choose  $\alpha$  and  $\beta$  so that the  $MSE_{\hat{p}_B}$  does not depend on  $p$ . We get  $\alpha = \beta = \frac{\sqrt{n}}{2}$ .



When  $p = 1/2$ , the Bayesian estimator (the blue line) has the biggest advantage over the MLE (the red line), since the expectation of the prior,  $Beta(\alpha, \beta)$ , is

$$\frac{\alpha}{\alpha + \beta} = \frac{1}{2}.$$

**Theorem (2.20).** Suppose that  $T$  is asymptotically unbiased estimator of  $\gamma(\theta)$  and  $var_{\theta}T \rightarrow 0$  as  $n \rightarrow \infty$  for all  $\theta \in \Theta$ . Then  $T$  is a consistent estimator of  $\gamma(\theta)$ .

*Proof.* Fix an arbitrary  $\varepsilon > 0$ , and  $\theta \in \Theta$ . By Markov inequality,

$$\begin{aligned} P_{\theta}(|T - \gamma(\theta)| > \varepsilon) &\leq \frac{E_{\theta}(T(X_1, \dots, X_n) - \gamma(\theta))^2}{\varepsilon^2} \\ &= \frac{MSE_{\theta}(T)}{\varepsilon^2} \\ &= \frac{\text{var}_{\theta}T + (\text{bias}_{\theta}T)^2}{\varepsilon^2} \xrightarrow{n \rightarrow \infty} 0. \end{aligned}$$

□

Remark:

we see from the proof that if  $T$  is an estimator of  $\gamma(\theta)$  and  $MSE_{\theta}T \rightarrow 0$  as  $n \rightarrow \infty$ , then  $T$  is consistent for  $\gamma(\theta)$ .

## 2.4 Best Unbiased Estimators

- Comparisons based on MSE may not yield a clean winner among estimators
- There is no “best MSE” estimator. Consider

$$\{\text{Bernoulli}(p), p \in (0, 1)\}.$$

Let

$$p_{\text{silly}} = 0.5.$$

This is silly because the estimator does not use the data at all, but

$$\begin{aligned} \text{MSE}_p(\hat{p}_{\text{silly}}) &= (0.5 - p)^2 \\ &= 0 \text{ when } p = 0.5. \end{aligned}$$

Now, we can devise such silly estimator for any  $p_0 \in (0, 1)$  :

$$\hat{p}_{\text{silly};p_0} = p_0 \rightarrow \text{MSE}_{p_0}(\hat{p}_{\text{silly};p_0}) = 0.$$

- MSE that uniformly minimize MSE of all possible estimators would have to be 0 for any  $p \in (0, 1)$ .

**Definition 2.20.** *An estimator  $T^*$  is called a uniform minimum variance unbiased estimator (UMVUE) of  $\gamma(\theta)$  if:*

1.  $T^*$  is unbiased:  $E_\theta T^* = \gamma(\theta)$
2.  $T^*$  is “best” in terms of the variance: if  $T$  is an arbitrary unbiased estimator of  $\gamma(\theta)$ ,

$$\forall \theta \in \Theta, \underbrace{\text{var}_\theta T^*}_{\text{MSE}_\theta T^*} \leq \underbrace{\text{var}_\theta T}_{\text{MSE}_\theta T}.$$

**Example 2.21.**  $X_1, \dots, X_n$  a random sample from  $Poisson(\lambda)$ ,  $\lambda \in (0, \infty)$ .  
We derived earlier an estimator of  $\lambda$ :

$$\hat{\lambda} = \bar{X}.$$

**Theorem 2.22** (Cramer-Rao Inequality). *Suppose that  $X_1, \dots, X_n$  is a random sample from  $P_\theta$ ,  $\theta \in \Theta \subset \mathbb{R}$ . Let  $T(X_1, \dots, X_n)$  be an unbiased estimator of  $\gamma(\theta)$ , i.e.*

$$\forall \theta \in \Theta, E_\theta T = \gamma(\theta).$$

Let  $X \sim P_\theta$ . Assume that the conditions (1), (2), (3) below holds:

(1) For all  $\theta \in \Theta$ ,  $P_\theta$  had a pdf/ pmf  $f(x; \theta)$  and

$$\frac{\partial f}{\partial \theta}$$

exists for all  $\theta \in \Theta$  and all  $x \in N_\theta$ .

(2)  $\forall \theta \in \Theta$ ,

$$E_\theta \left( \frac{\partial \log f}{\partial \theta}(X; \theta) \right) = 0$$

and

$$E_\theta \left( \left( \frac{\partial \log f}{\partial \theta}(X; \theta) \right)^2 \right) = I(\theta) \in (0, \infty)$$

for all  $\theta \in \Theta$ . Here,  $I(\theta)$  is called the Fisher Information.

(3)  $\text{var}_\theta T(X_1, \dots, X_n) < \infty$  for all  $\theta \in \Theta$  and

$$\sum_{i=1}^n E_\theta \left\{ T(X_1, \dots, X_n) \cdot \frac{\partial \log f}{\partial \theta}(X_i; \theta) \right\} = \gamma'(\theta)$$

for all  $\theta \in \Theta$ .

Then

$$\text{var}_\theta T(X_1, \dots, X_n) \geq \frac{(\gamma'(\theta))^2}{n \cdot I(\theta)}.$$

*Proof.* Cauchy-Schwarz inequality:

$$(\text{cov}(Z, W))^2 \leq \text{var}Z \cdot \text{var}W.$$

□

### Remarks

- Note that if  $X \sim P_\theta$ ,

$$P_\theta(X \in \{x : f(x; \theta) > 0\}) = 1.$$

So we can assume wlog that  $f(x; \theta) > 0$  for all  $x \in N_\theta$  and  $\theta \in \Theta$ . Then

$$\frac{\partial \log f}{\partial \theta} = \frac{\frac{\partial f}{\partial \theta}}{f}$$

exists for all  $\theta \in \Theta$  and  $x \in N_\theta$ .

- Assumptions (2) and (3) really mean that we can interchange differentiation and either integration or summation as the case may be.
- Check if it is an exponential family

**Example 2.23.**  $X_1, \dots, X_n$  us Bernoulli( $p$ ),  $p \in (0, 1)$ .  $\bar{X}$  is UMVUE for  $p$ .

Recall that Cauchy-Schwarz inequality,

$$\text{cov}(X, Y) \leq \sqrt{\text{var}X \text{var}Y}.$$

Equality holds if and only if  $\exists a, b \in \mathbb{R}$  so that

$$Y = aX + b \text{ a.s.}$$

Denoting  $T = T(X_1, \dots, X_n)$ , an unbiased estimator of  $\gamma(\theta)$  with finite variance and

$$W = \sum_{i=1}^n \frac{\partial}{\partial \theta} \log f(X_i; \theta)$$

then we have

**Corollary 2.24.** *Under the condition of the CR theorem (Thm 2.22),  $T$  attains the CR lower bound if and only if*

$$a(\theta) \cdot (T - \gamma(\theta)) = W \quad P_\theta - \text{a.s.}$$

**Example 2.23 (cont'd)**  $X_1, \dots, X_n$ , a random sample from Bernoulli( $p$ ),  $p \in (0, 1)$ .

$$\begin{aligned} W &= \sum_{i=1}^n \frac{\partial}{\partial p} \log f(X_i; p) \\ &= \sum_{i=1}^n \left( \frac{X_i}{p} + \frac{(1 - X_i)}{1 - p} \right) \\ &= \frac{n\bar{X} - np}{p(1 - p)}. \end{aligned}$$

Suppose we wish to estimate the ODDs

$$\gamma(\theta) = \frac{p}{1 - p}$$



In order for  $T$  to attain the CR lower bound

$$\frac{p}{n(1-p)^3},$$

we have to have that  $T = a(n)\bar{X} + b(n)$ , but  $ET = a(n) \cdot p + b(n) \neq \frac{p}{1-p}$  for all  $p \in (0, 1)$ . Hence, the CR lower bound for estimating the odds cannot be attained.

**Definition 2.25** (One-parameter exponential family). *A family of PDFs/PMFs is called a one-parameter exponential family in  $c(\theta)$  and  $T(x)$ , if, for all  $\theta \in \Theta \subset \mathbb{R}$ ,*

$$f(x; \theta) = 1_A(x) \exp \{c(\theta)T(x) + d(\theta) + S(x)\}$$

for some set  $A \subset \mathbb{R}$  which does not depend on  $\theta$  and is a Borel set,  $c : \Theta \rightarrow \mathbb{R}$ , and  $S, T : \mathbb{R} \rightarrow \mathbb{R}$  Borel-measurable, and  $T$  is not a.s. constant on  $A$ .

**Example 2.26.** *Bernoulli( $p$ ):*

$$f(x; p) = p^x (1-p)^{1-x}, x \in \{0, 1\}.$$

$$A = \{0, 1\}.$$

On  $A$ ,

$$\begin{aligned} f(x; p) &= \exp \{x \cdot \log p + (1-x) \cdot \log(1-p)\} \\ &= \exp \left\{ \underbrace{x}_{T(x)} \cdot \underbrace{\log \frac{p}{1-p}}_{c(p)} + \underbrace{\log(1-p)}_{d(p)} \right\}. \end{aligned}$$

**Remark**

One can prove that for  $\Theta = (a, b)$ ,  $-\infty \leq a < b \leq \infty$ ,  $c : \Theta \rightarrow \mathbb{R}$  is continuously differentiable with  $c'(\theta) > 0$  for all  $\theta \in \Theta$ , then the assumptions of the CR Theorem 2.22 are fulfilled. Since

$$\frac{\partial}{\partial \theta} \log f(x; \theta) = c'(\theta)T(x) + d'(\theta)$$

than

$$Z = \frac{1}{n} \sum_{i=1}^n T(X_i)$$

is an UMVUE of  $\gamma(\theta) = ET(X)$  (assuming  $ET^2(X) < \infty$ ) by Theorem 2.22.

**Example 2.27** (Uniform  $(0, \theta)$ ). *A unbiased estimator of  $\theta$  is*

$$T = \frac{n+1}{n} X(n).$$

$$\text{var}T = \frac{\theta^2}{n(n+2)} \ll \frac{\theta^2}{n}, \text{ CR lower bound.}$$

. *Hence, we need a deeper theory to find UMVUE.*

### 3 Chapter 3: Sufficiency and Completeness

#### 3.1 Sufficiency

Can we summarize the data without losing information about  $\theta$ ?

**Notation:** the support of  $(X_1, \dots, X_n)$ , the so called sample space, is denoted by  $\mathcal{X}$ .

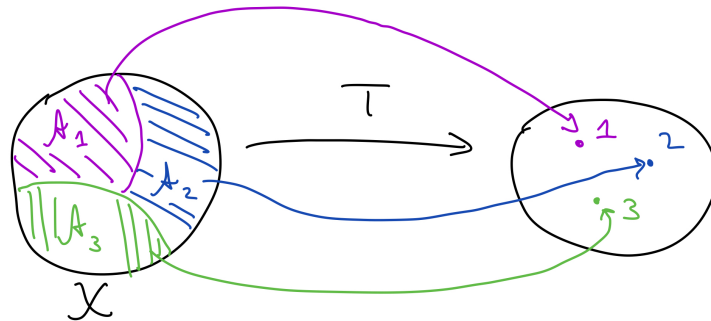
**Basic observation** Any statistic  $T$  induces a partition of  $\mathcal{X}$ . Indeed, let

$$\tau = \{t : t = T(\tilde{x}) \text{ for some } \tilde{x} \in \mathcal{X}\}.$$

The sets

$$\mathcal{A}_t = T^{-1}\{t\} = \{\tilde{x} \in \mathcal{X} : T(\tilde{x}) = t\}$$

form a partition of the sample space.



The statistic  $T$  summarizes the data (i.e. reduces information).  $T = t$  really means that  $(X_1, \dots, X_n) \in \mathcal{A}_t$ .

$T$  contains all relevant information about  $\theta$  if the exact value of  $\tilde{x} \in \mathcal{A}_t$  contains no additional information about  $\theta$ .

**Definition 3.1** (Sufficient statistic). *A statistic  $T(X_1, \dots, X_n)$  is a sufficient statistic for  $\theta$  if the conditional distribution of  $(X_1, \dots, X_n)$  given  $T(X_1, \dots, X_n) = t$  does not depend of  $\theta$ .*

**Example 3.2.**

- $(X_1, \dots, X_n)$  is sufficient for  $\theta$ : the conditional distribution of  $(X_1, \dots, X_n)$  given  $(X_1, \dots, X_n) = x$  is degenerate.
- $X_1, \dots, X_n$  be a random sample from Bernoulli( $p$ ),  $p \in (0, 1)$ .

$$T(X_1, \dots, X_n) = \sum_{i=1}^n X_i.$$

Here,  $\mathcal{X} = \{0, 1\}^n$ ,  $T = \{0, 1, \dots, n\}$ ,

$$\mathcal{A}_t = \{(x_1, \dots, x_n) \in \{0, 1\}^n : \sum_{i=1}^n x_i = t\}.$$

For all  $(x_1, \dots, x_n) \in \mathcal{X}$ ,  $t \in \tau$ ,

$$P_\theta((X_1, \dots, X_n) = (x_1, \dots, x_n) | T(X_1, \dots, X_n) = t) = \begin{cases} 0 & \text{if } x \notin \mathcal{A}_t \\ \frac{1}{\binom{n}{t}} & \text{if } x \in \mathcal{A}_t \end{cases}$$

does not depend on  $p$ , so  $T = \sum_{i=1}^n$  is sufficient for  $p$ .

**Theorem 3.3** (Neyman-Fisher Factorization). *Let  $f(x_1, \dots, x_n; \theta)$  denote the joint pdf/pmf of  $(X_1, \dots, X_n)$ . A statistic  $T$  is sufficient for  $\theta$  if and only if for all  $\theta \in \Theta$ , there exists measurable function  $g_\theta$ ,  $h$  so that*

$$f(x_1, \dots, x_n; \theta) = g_\theta(T(x_1, \dots, x_n)) \cdot h(x_1, \dots, x_n).$$

*Proof.*

□

**Example 3.4.**  $X_1, \dots, X_n$  is a random sample from  $N(\mu, \sigma^2)$ ,  $\mu \in \mathbb{R}$ ,  $\sigma^2 > 0$ .

$$f(x_1, \dots, x_n; \mu, \sigma^2) = \left(\frac{1}{2\pi}\right)^{n/2} \left(\frac{1}{\sigma^2}\right)^{n/2} \exp\left(-\frac{\sum_{i=1}^n (x_i - \mu)^2}{2\sigma^2}\right).$$

Clearly,  $(X_1, \dots, X_n)$  is sufficient for  $(\mu, \sigma^2)$ . But

$$\begin{aligned} & \sum_{i=1}^n (x_i - \mu)^2 \\ &= \sum_{i=1}^n (x_i - \bar{x})^2 + n(\bar{x} - \mu)^2 \\ &= (n-1)s^2 + n(\bar{x} - \mu)^2 \end{aligned}$$

$$f(x_1, \dots, x_n; \mu, \sigma^2) = \underbrace{\left(\frac{1}{2\pi}\right)^{n/2}}_{h(\bar{x})} \cdot \underbrace{\left(\frac{1}{\sigma^2}\right)^{n/2} \exp\left(-\frac{(n-1)s^2 + n(\bar{x} - \mu)^2}{2\sigma^2}\right)}_{g_{\mu, \sigma^2}(\bar{x}, s^2)}$$

Using Thm 3.3 (Neyman-Fisher factorization), we conclude that  $(\bar{X}, S^2)$  is sufficient for  $(\mu, \sigma^2)$ . Assume now that  $\sigma^2$  is known. Here,  $(\bar{X}, S^2)$  is sufficient for  $\mu$ . But, we can also write

$$f(x_1, \dots, x_n; \mu, \sigma^2) = \underbrace{\left(\frac{1}{2\pi}\right)^{n/2} \left(\frac{1}{\sigma^2}\right)^{n/2} \exp\left(-\frac{(n-1)s^2}{2\sigma^2}\right)}_{h(\bar{x})} \cdot \underbrace{\exp\left(-\frac{n(\bar{x} - \mu)^2}{2\sigma^2}\right)}_{g_{\mu}(\bar{x})}$$

Hence,  $\bar{X}$  is sufficient for  $\mu$ .

**Remark:** Sufficient statistic is generally not unique. Some statistics achieve greater data reduction than others. Also, the dimension of parameters and the dimension of statistics are unrelated.

**Example 3.5.** Consider a random sample from  $U(\theta, \theta + 1)$ ,  $\theta \in \mathbb{R}$ .

$$\begin{aligned} & f(x_1, \dots, x_n; \theta) \\ &= \begin{cases} 1, & \text{if } \theta < x_i < \theta + 1 \\ 0, & \text{otherwise} \end{cases} \\ &= \underbrace{1(\min_{1 \leq i \leq n} x_i > \theta) \cdot 1(\max_{1 \leq i \leq n} x_i < \theta + 1)}_{g_\theta(\min_{1 \leq i \leq n} x_i; \max_{1 \leq i \leq n} x_i)} \end{aligned}$$

Using the Neyman-Fisher factorization, we have that

$$(\min_{1 \leq i \leq n} X_i, \max_{1 \leq i \leq n} X_i)$$

is sufficient for  $\theta$ .

**Example 3.6.** Consider a random sample from  $U(0, \theta)$

Consider a random sample from  $U(0, \theta)$ ,  $\theta > 0$ .

$$\begin{aligned} & f(x_1, \dots, x_n; \theta) \\ &= \begin{cases} (\frac{1}{\theta})^n, & \text{if } 0 < x_i < \theta \\ 0, & \text{otherwise} \end{cases} \\ &= \underbrace{(\frac{1}{\theta})^n \cdot 1(\max_{1 \leq i \leq n} x_i < \theta)}_{g_\theta(\max_{1 \leq i \leq n} x_i)} \cdot \underbrace{1(\min_{1 \leq i \leq n} x_i > 0)}_{h(x_1, \dots, x_n)} \end{aligned}$$

By the Neyman-Fisher factorization,  $\max_{1 \leq i \leq n} X_i$  is sufficient for  $\theta$ .

## 3.2 The Rao-Blackwell Theorem

Recall  $X, Y$  random variables

$$E(X) = E(E(X|Y))$$

and  $E(X|Y)$  is a measurable function of  $Y$ .

$$\text{var}(X) = E(\text{var}(X|Y)) + \text{var}(E(X|Y)).$$

**Theorem 3.7** (Rao-Blackwell Theorem). *Let  $W$  be an unbiased estimator of  $\gamma(\theta)$  with finite variance, and  $T$  be a sufficient statistic for  $\theta$ . Let*

$$W^* = E(W|T).$$

*Then*

(a)  $W^*$  is an unbiased estimator of  $\gamma(\theta)$ .

(b) For all  $\theta \in \Theta$  :

$$\text{var}_\theta W^* \leq \text{var}_\theta W.$$

**Example 3.8.**

**Remark**

- Process of conditioning on a sufficient statistic is called “Rao-Blackwellization”.
- Theorem 3.7 implies that an UMVUE (if it exists) needs to be based on a sufficient statistic.

**Corollary 3.9.** *Let  $W$  be an estimator of  $\gamma(\theta)$  with finite variance, but not necessarily unbiased. Let  $T$  be a sufficient statistic for  $\theta$ . Then for*

$$W^* = E(W|T),$$

$$MSE_\theta(W^*) \leq MSE_\theta(W) \quad \forall \theta \in \Theta.$$

### 3.3 Completeness

Suppose that  $T$  is a statistic and  $g$  is a measurable function such that

$$\forall \theta \in \Theta, E_{\theta}g(T) =$$

we have that

$$\forall \theta \in \Theta, E_{\theta}g(T) = 0.$$

Assume, for simplicity  $\Theta \in \mathbb{R}$  and we wish to estimate  $\theta$ . Suppose  $W$  is an unbiased estimator of  $\theta$ . Suppose that  $g(T)$  is not degenerate (i.e. is a constant a.s.). Then for any  $a \in \mathbb{R}$ ,

$$W_a = W + g(T) \cdot a$$

then  $W_a$  is also an estimator of  $\theta$  :

$$\begin{aligned} E_{\theta}(W_a) &= E_{\theta}(W) + a \cdot E_{\theta}(g(T)) \\ &= \theta + a \cdot 0 = \theta. \end{aligned}$$

Assume further that  $W$  and  $g(T)$  have a finite variance. Suppose that  $cov_{\theta_0}(W, g(T)) \neq 0$  for some  $\theta_0 \in \Theta$ . Then, WLOG assume  $cov_{\theta_0}(W, g(T)) < 0$ :

$$\begin{aligned} var_{\theta_0} &= var_{\theta_0}(W) + a^2 \cdot var_{\theta_0}(g(T)) \\ &\quad + 2a \cdot cov_{\theta_0}(W, g(T)) \end{aligned}$$

Then,

$$\begin{aligned} var_{\theta_0} - var_{\theta_0}(W) &= a^2 \cdot var_{\theta_0}(g(T)) \\ &\quad + 2a \cdot cov_{\theta_0}(W, g(T)). \end{aligned}$$



The RHS is negative if  $a > 0$  and

$$a \cdot \text{var}_{\theta_0} g(T) < -2 \cdot \text{cov}_{\theta_0}(W, g(T))$$

$$a < \underbrace{\frac{-2 \cdot \text{cov}_{\theta_0}(W, g(T))}{\text{var}_{\theta_0}(g(T))}}_{=a^* > 0}$$

Hence, for  $a \in (0, a^*)$ ,

$$\text{var}_{\theta_0} W_a < \text{var}_{\theta_0} W.$$

Note that if  $T$  is complete, no such  $a^*$  exists.

**Definition 3.10** (Completeness). *A statistic  $T$  is called complete, if the family  $\{P_\theta^T, \theta \in \Theta\}$  is complete, meaning that if for any measurable  $g : T \rightarrow \mathbb{R}$  such that*

$$\forall \theta \in \Theta, \mathbb{E}(g(t)) = 0,$$

*we have*

$$\forall \theta \in \Theta, P_\theta(g(T) = 0) = 1.$$

**Remark:**  $T$  is complete if  $\forall \theta \in \Theta, E_\theta(g(T)) = 0$  implies that  $g(T) = 0$   $[P]$  a.e. Then, clearly,  $\text{cov}_\theta(W, g(T)) = 0$  for all  $\theta \in \Theta$ , for any unbiased estimate  $W$ .

**Example 3.11.** *Completeness tells us something about the size of*

$$\{P_\theta^T, \theta \in \Theta\}.$$

*Consider  $X_1, \dots, X_n$  a random sample from Bernoulli( $p$ ),  $p \in \Theta \subset (0, 1)$ . Take  $T = \sum_{i=1}^n X_i$ . Then  $T \sim \text{Binomial}(n, p)$ . Hence*

$$E_p(g(T)) = \sum_{k=0}^n g(k) \binom{n}{k} p^k (1-p)^{n-k}.$$

So  $E_p(g(T)) = 0$  for all  $p \in \Theta$  means that

$$0 = \sum_{k=0}^n g(k) \underbrace{\binom{n}{k}}_{a_k} \cdot (1-p)^n \cdot \underbrace{\left(\frac{p}{1-p}\right)^k}_r$$

$$(*) \quad 0 = \sum_{k=0}^n a_k r^k, \quad p \in \Theta$$

For  $T$  to be complete, we need to conclude that  $g(k) = 0$  for all  $k \in \{0, \dots, n\}$ , i.e.  $a_k = 0$  for all  $k \in \{0, \dots, n\}$ .

- If  $\Theta = (0, 1)$ , then  $r = \frac{p}{1-p} \in (0, \infty)$ . Hence,  $(*)$  means that the polynomial vanishes for all  $r \in (0, \infty)$ , and that indeed implies that  $a_k = 0$  for all  $k \in \{0, \dots, n\}$ , so  $T$  is complete.
- If  $\Theta$  is finite and  $|\Theta| \leq n$ , it may well happen that  $a_k \neq 0$  for some  $k$ . For example, if  $\Theta = \{1/2\}$ , then  $(*)$  becomes (say  $n = 1$ ):

$$0 = g(0) + g(1)$$

which does not imply

$$g(0) = g(1) = 0.$$

Hence,  $T$  is NOT complete.

**Example 3.12.** Consider a random sample  $X_1, \dots, X_n$  from  $U(0, \theta)$ ,  $\theta > 0$ .

$$T = \max_{i \leq i \leq n} X_i.$$

Then,

$$P_\theta(T \leq t) = \prod_{i=1}^n P_\theta(X_i \leq t) = \begin{cases} (t/\theta)^n, & t \in (0, \theta) \\ 0, & t \leq 0 \\ 1, & t \geq \theta \end{cases}$$

So  $T$  has a pdf:

$$f_{\theta}^T(t) = \frac{n}{\theta^n} \cdot t^{n-1}, \quad t \in (0, \theta).$$

Suppose that  $g$  is measurable and such that  $E_{\theta}g(T) = 0$  for all  $\theta > 0$ . Suppose that  $g$  is Riemann-integrable.

$$E_{\theta}g(T) = 0 \iff 0 = \int_0^{\theta} g(t) \cdot \frac{n}{\theta^n} \cdot t^{n-1} dt$$

Fix  $\theta \in \Theta$  arbitrary. Then  $E_{\theta}g(T) = 0$  implies

$$\begin{aligned} 0 &= \frac{\partial}{\partial \theta} \int_0^{\theta} g(t) \frac{n}{\theta^n} t^{n-1} dt \\ &= \left( \frac{\partial}{\partial \theta} \theta^{-n} \right) \cdot \underbrace{\theta^n \int_0^{\theta} g(t) \frac{n}{\theta^n} t^{n-1} dt}_{=0 \text{ because } E_{\theta}g(T)=0} \\ &\quad + \theta^{-n} \cdot \frac{\partial}{\partial \theta} \int_0^{\theta} g(t) n \cdot t^{n-1} dt \\ &= \theta^{-n} [g(\theta) n \cdot \theta^{n-1}] \\ &= \frac{g(\theta) \cdot n}{\theta} \text{ by Leibnitz rule} \end{aligned}$$

Hence,  $g(\theta) = 0$  implies  $g(t) = 0$  for  $t > 0$  for any  $\theta > 0$ . Then,  $P_{\theta}(g(T) = 0) = 1$  for all  $\theta > 0$ . Hence,  $T$  is complete.

**Theorem 3.13** (Lehmann-Scheffe).  $X_1, \dots, X_n$  a random sample from  $P_{\theta}$ ,  $\theta \in \Theta$ . Suppose that  $T$  is a sufficient and complete statistic. Let  $\gamma(\theta)$  be a real-valued parameter, and let  $W$  be an unbiased estimator of  $\gamma(\theta)$  with finite variance. Then

$$W^* = E(W|T)$$

is UMVUE for  $\gamma(\theta)$ .

**Remark:**

- We see from the proof that the UMVUE is a.s. unique.

- If  $T$  is complete and sufficient and  $W = h(T)$  is unbiased, then  $W$  is UMVUE.

**Example 3.14.**

- $T = \max_{1 \leq i \leq n} X_i$  is complete.
- $T$  is sufficient
- $\frac{n+1}{n}T$  is an unbiased estimator of  $\theta$ .

Hence, by Lehmann-Scheffe theorem,  $\frac{n+1}{n} \max_{1 \leq i \leq n} X_i$  is UMVUE.

**Theorem 3.15.** Suppose  $X_1, \dots, X_n$  are iid from a distribution in a  $J$ -parameter exponential family, that is, the PDF/PMF has the form

$$f(x; \theta) = 1(x \in A) \exp\left\{\sum_{j=1}^J c_j(\theta)T_j(x) + d(\theta) + S(x)\right\}$$

where  $J \geq 1$ ,  $A \subset \mathbb{R}$  is a Borel set independent of  $\theta$ ,  $c_1, \dots, c_J, d : \Theta \rightarrow \mathbb{R}$ ;  $T_1, \dots, T_J, S : \mathbb{R} \rightarrow \mathbb{R}$  measurable and  $T_1, \dots, T_J$  are not a.s. constant. Then

$$T = \left( \sum_{i=1}^n T_1(X_i), \dots, \sum_{i=1}^n T_J(X_i) \right)$$

is sufficient for  $\theta$ . If

$$\{(c_1(\theta), \dots, c_J(\theta)) : \theta \in \Theta\}$$

contains an open subset in  $\mathbb{R}^J$ ,  $T$  is complete.

**Example 3.16.**

- Bernoulli:

$$\begin{aligned} f(x; p) &= p^x(1-p)^{1-x}1(x \in \{0, 1\}) \\ &= 1(x \in \{0, 1\}) \exp\left\{x \cdot \log \frac{p}{1-p} + \log(1-p)\right\} \end{aligned}$$

where  $J = 1$ ,  $S(x) = 0$ . By Theorem 3.15,  $\sum_{i=1}^n X_i$  is sufficient for  $p$ .

The set

$$\left\{ \log \frac{p}{1-p}, p \in (0, 1) \right\} = (-\infty, \infty).$$

Hence,  $\sum_{i=1}^n X_i$  is complete.

- Uniform:  $f(x; \theta) = \frac{1}{\theta} 1(x \in (0, \theta))$  is not an exponential form since  $A = (0, \infty)$  depends on  $\theta$ .

## 4 Chapter 4: Hypothesis Tests

### 4.1 Basic terminology of hypothesis testing

**Definition 4.1** (Hypothesis). *A hypothesis is a statement about a population parameter. Given a parametric model for the population distribution, viz*

$$\{P_\theta, \theta \in \Theta\}$$

*we have*

- *the null hypothesis (“the null”)*

$$H_0 : \theta \in \Theta_0$$

*where  $\Theta_0 \subset \Theta$  is some fixed subset of the parameter space.*

- *the alternative hypothesis (the “alternative”)*

$$H_1 : \theta \notin \Theta_0$$

*When  $|\Theta_0| = 1$ ,  $H_0$  is called simple; otherwise, it is called composite, and analogously for  $H_1$ .*

**Definition 4.2** (Hypothesis test). *A hypothesis test is a decision rule that specifies for which sample values  $H_0$  is rejected and for which it is not. Formally, a hypothesis test is a measurable map*

$$\psi : \chi \rightarrow [0, 1].$$

*The observed value  $\psi(x_1, \dots, x_n)$  is the probability of rejecting  $H_0$  when*

$$(X_1, \dots, X_n) = (x_1, \dots, x_n).$$

•

$$R = \{(x_1, \dots, x_n) \in \mathcal{X} : \psi(x_1, \dots, x_n) = 1\}$$

*is called the rejection region.*

•

$$A = \{(x_1, \dots, x_n) \in \mathcal{X} : \psi(x_1, \dots, x_n) = 0\}$$

*is called the acceptance region.*

•

$$U = \{(x_1, \dots, x_n) \in \mathcal{X} : \psi(x_1, \dots, x_n) \in (0, 1)\}$$

*is called the randomization region.*

If  $U \neq \emptyset$ ,  $\psi$  is called a randomized test.

**Example 4.3.** *Coffee bean: good - 0, spoiled - 1*

$X_1, \dots, X_n$  sample of coffee beans

• *test statistic:*

$$T = \sum_{i=1}^n X_i = \text{“number of spoiled beans”}$$

• *pick  $c \in \{0, \dots, n+1\}$*

•

$$\psi(X_1, \dots, X_n) = \begin{cases} 1, & T \geq c \\ 0, & T < c \end{cases} = 1(T \geq c)$$

Any test can have 4 possible outcomes:  
Decision

		Decision	
		Accept $H_0$	Reject $H_0$
TRUTH	$H_0$ is true	✓	Type I error "false positive"
	$H_0$ is false	Type II error "false negative"	✓

- Medical test :
  - $H_0$ : healthy
  - $H_1$ : infected
- Trial :
  - $H_0$ : innocent
  - $H_1$ : guilty
- Exam :
  - $H_0$ : student deserves to pass
  - $H_1$ : student does not deserve to pass



		Exam	
		pass	fail
TRUTH	pass	✓	Type I failing a good student
	fail	Type II passing a poor student	✓

Extreme exams:

- super easy:
  - ⇒ everyone passes
  - ⇒ type I error does not occur
  - ⇒ type II error blows up.

- super tough
  - every fails
  - type 2 error does not occur
  - type 1 error blows up
- Department chair: make sure that at most 5% (or  $\alpha\%$ ) of good students fails  $\implies$  control the Type 1 error  $\implies$  LEVEL
- While controlling type 1 error, we can try to minimize the type 2 error, or maximize the power of the test (to detect the alternative, i.e. fail poor students)

**Definition 4.4** (Power function). *The power function of a hypothesis test  $\psi$  is*

$$B_\psi : \Theta \rightarrow [0, 1]$$

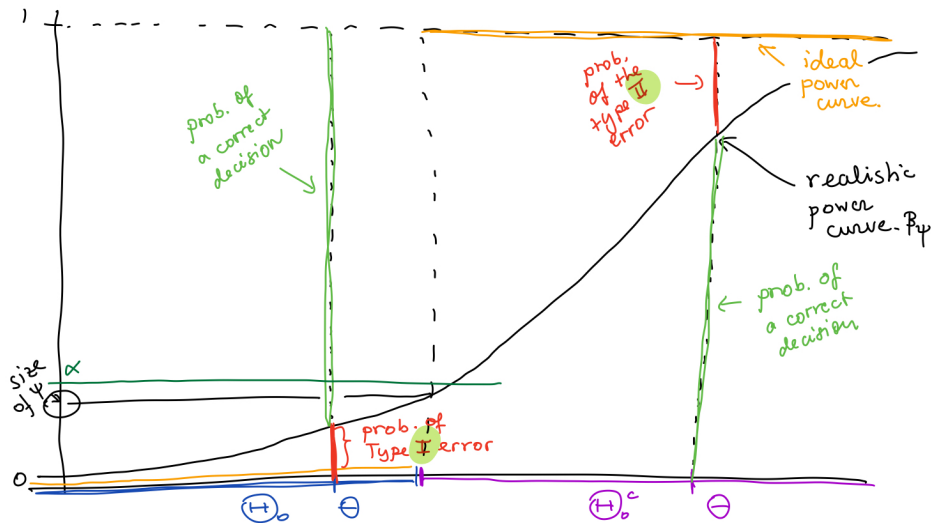
$$\theta \rightarrow E_\theta(\psi(X_1, \dots, X_n))$$

If  $\psi$  is not randomized,  $B_\psi(\theta)$  is the probability of rejecting  $H_0$ . For a given  $\alpha \in [0, 1]$ ,  $\psi$  is called a level- $\alpha$  test if

$$\forall \theta \in \Theta_0 : B_\psi(\theta) \leq \alpha.$$

The size of  $\psi$  is  $\sup_{\theta \in \Theta_0} B_\psi(\theta)$ .

" The power curve says it all "



A level- $\alpha$  test controls type 1 error, but not necessarily the type 2 error.

- Rejecting  $H_0$  is a “safe” decision
- Accepting  $H_0$  is NOT a “safe” decision. That’s why we say “the data do not provide sufficient evidence to reject  $H_0$ ” or “do not reject  $H_0$ ”.
- If possible, the scientific hypothesis we wish to prove should be the alternative. Sometimes, it is not possible. For example, we want to know if the snowfall is from a normal distribution.

**Example 4.1 (cont’d)**

$$H_0 : \theta \leq \frac{1}{100} \quad H_1 : \theta > \frac{1}{100}$$

$$T = \sum_{i=1}^n X_i \sim \text{Binomial}(n, \theta).$$

$$B_\psi(\theta) = P_\theta(T \geq c) = \sum_{k=c}^n \binom{n}{k} \theta^k (1 - \theta)^{n-k}$$

- if  $c = 0$ ,  $B_\psi(\theta) = 1$  for all  $\theta \in (0, 1)$ .
- if  $c = n + 1$ ,  $B_\psi(\theta) = 0$  for all  $\theta \in (0, 1)$
- if  $c \in \{1, \dots, n\}$  :  $B_\psi$  is strictly increasing in  $\theta$ .  $\implies$  The size of  $\psi$  is  $B_\psi(\frac{1}{100})$ .
- To choose  $c$ :
  - Control type 1 error:

$$B_\psi\left(\frac{1}{100}\right) \leq \alpha = 0.05$$

The larger  $c$ , the smaller the size.

- Maximize the power: maximize  $B_\psi$  for  $\theta > 1/100$ . The smaller  $c$ , the larger the power.
- Note: typically, increasing the sample size leads to a better power.

## 4.2 Likelihood Ratio Test

General strategy how to construct tests. Typically, we construct a test statistic

$$W(X_1, \dots, X_n)$$

and identify values in the sample space  $\chi$  for which  $W$  has an unlikely value if  $H_0$  holds. This set of values in  $\chi$  will form a rejection region  $R$ . The (non-randomized) test will be

$$\psi(X_1, \dots, X_n) = 1((X_1, \dots, X_n) \in R).$$

For test problems about the parameter  $\theta$ ,

$$H_0 : \theta \in \Theta_0 \quad H_1 : \theta \notin \Theta_0$$

a large class of tests can be obtained as follows:

**Definition 4.5** (Likelihood ratio test). *The likelihood ratio statistic for testing*

$$H_0 : \theta \in \Theta_0 \quad H_1 : \theta \notin \Theta_0$$

is  $\lambda(X_1, \dots, X_n)$  given, at any  $(x_1, \dots, x_n)$  by,

$$\lambda = \frac{\sup_{\theta \in \Theta_0} L(\theta; x_1, \dots, x_n)}{\sup_{\theta \in \Theta} L(\theta; x_1, \dots, x_n)}.$$

A likelihood ratio test (LRT) has the rejection region

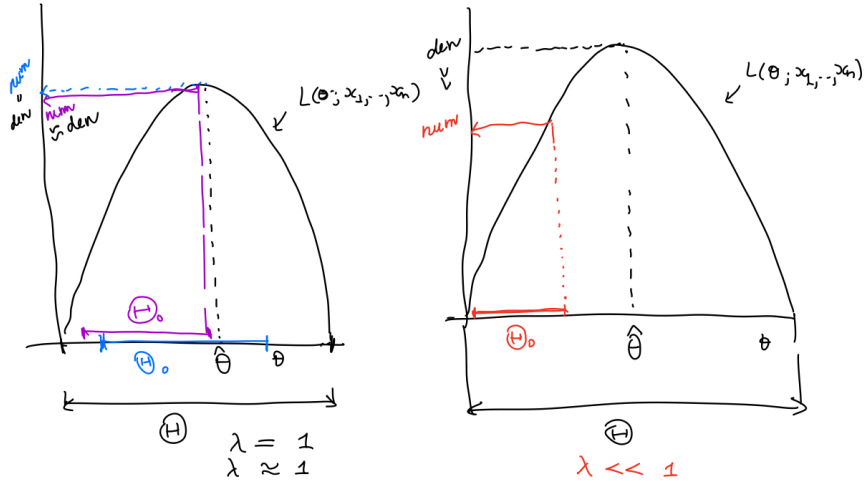
$$R = \{(x_1, \dots, x_n) : \lambda(x_1, \dots, x_n) \leq c\}$$

for some suitable chosen critical value  $c$ , chosen as a function of  $\alpha$  (the level of the test).

Illustration:

1)  $H_0$  holds

2)  $H_1$  holds



How do we calculate the LR statistic  $\lambda$ ?

- If  $\hat{\theta}$  is MLE of  $\theta$  and  $\hat{\theta}_0$  is  $\hat{\theta}_0 = \operatorname{argmax}_{\theta \in \Theta_0} L(\theta; X_1, \dots, X_n)$ , then

$$\lambda = \frac{L(\hat{\theta}_0; x_1, \dots, x_n)}{L(\hat{\theta}; x_1, \dots, x_n)}$$

**Example 4.6.** We wish to test  $H_0 : p \leq p_0$  vs  $H_1 : p > p_0$  based on a random sample  $X_1, \dots, X_n$  from Bernoulli( $p$ ) (viz. Example 4.1). To construct a LRT, recall

$$L(p; x_1, \dots, x_n) = p^{n\bar{x}}(1-p)^{n(1-\bar{x})}, \quad p \in [0, 1]$$

we already know (Ex. 2.9) that the MLE of  $p$  is  $\bar{X}$ .

$$\hat{p}_0 = \operatorname{arg} \max_{0 \leq p \leq p_0} L(p; x_1, \dots, x_n) = \min(p_0, \bar{x}).$$

### 4.3 p-value

**Definition 4.7.** Let  $W(X_1, \dots, X_n)$  be a test statistic such that small (large) value of  $W$  give evidence against  $H_0$  (are unlikely under  $H_0$ ). For each

$$(x_1, \dots, x_n) \in \mathcal{X},$$

let

$$p(x_1, \dots, x_n) = \sup_{\theta \in \Theta_0} P_{\theta}(W(X_1, \dots, X_n) \leq (\geq) \underbrace{W(x_1, \dots, x_n)}_{\text{observed value of } W}),$$

“probability of observing a value of  $W$  that is even more unlikely under  $H_0$  than the one actually observed”

The random variable  $p(X_1, \dots, X_n)$  is called the p-value.

Definition 4.7 Let  $W(X_1, \dots, X_n)$  be a test statistic such that small (large) values of  $W$  give evidence against  $H_0$  (are unlikely under  $H_0$ ) For each  $(x_1, \dots, x_n) \in \mathcal{X}$ , let

$$* p(x_1, \dots, x_n) = \sup_{\theta \in \Theta_0} P_{\theta}(W(X_1, \dots, X_n) \leq (\geq) \underbrace{W(x_1, \dots, x_n)}_{\text{observed value of } W})$$

“probability of observing a value of  $W$  that is even more unlikely under  $H_0$  than the one actually observed”

The random variable  $p(X_1, \dots, X_n)$  is called the p-value

Note: the p-value is NOT the probability that  $H_0$  holds!

**Example 4.8** (p-value of a LRT).

$$p(x_1, \dots, x_n) = \sup_{\theta \in \Theta_0} (\lambda(X_1, \dots, X_n) \leq \lambda(x_1, \dots, x_n)).$$

**Example 4.9** (Bernoulli).

**Theorem 4.10.** *In the context of Definition 4.7, the test that rejects  $H_0$  if  $p(X_1, \dots, X_n) \leq \alpha$  is a level- $\alpha$  test for all  $\alpha \in [0, 1]$ .*

**Lemma 4.11.** *For any random variable  $Y$  with distribution function  $G$ ,  $P(G(Y) \leq u) \leq u$  for all  $u \in [0, 1]$ .*

*Proof.* wlog:

$$p(x_1, \dots, x_n) = \sup_{\theta \in \Theta_0} P_\theta(W \leq w(x_1, \dots, x_n)).$$

For all  $\theta \in \Theta$ , let

$$\begin{aligned} p_\theta(x_1, \dots, x_n) &= P_\theta(W(X_1, \dots, X_n) \leq w(x_1, \dots, x_n)) \\ &= F_\theta^W(W(x_1, \dots, x_n)) \end{aligned}$$

From Lemma 4.11

$$\begin{aligned} &P_\theta(p_\theta(X_1, \dots, X_n) \leq \alpha) \\ &= P_\theta(F_\theta^W(W(X_1, \dots, X_n)) \leq \alpha) \leq \alpha \end{aligned}$$

Hence, for all  $\theta^* \in \Theta_0$

$$P_{\theta^*}(p(X_1, \dots, X_n) \leq \alpha) \leq P_{\theta^*}(p_{\theta^*}(X_1, \dots, X_n) \leq \alpha) \leq \alpha$$

since

$$p(X_1, \dots, X_n) = \sup_{\theta \in \Theta_0} p_\theta(X_1, \dots, X_n) \geq p_{\theta^*}(X_1, \dots, X_n)$$

Note: if you report the p-value

- the reader can choose  $\alpha$
- the smaller the p-value, the stronger the evidence against  $H_0$ .

□

## 4.4 Small Sample Tests for Normal Samples

Throughout this lecture:  $X_1, \dots, X_n$  is a random sample from  $N(\mu, \sigma^2)$ .

**Example 4.12** (z-test). Assume that  $\sigma^2 \equiv \sigma_0^2$  is KNOWN and we wish to test

$$H_0 : \mu = \mu_0 \text{ vs } H_1 : \mu \neq \mu_0$$

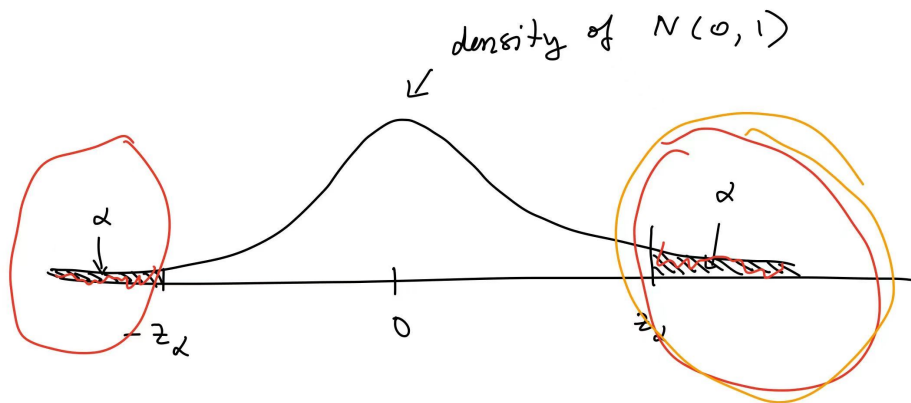
The Z statistic is

$$\sqrt{n} \frac{\bar{X} - \mu_0}{\sigma_0} \sim N(0, 1).$$

**Definition 4.13** ( $(1-\alpha) \cdot 100\%$  quantile of  $N(0, 1)$ ). The  $(1-\alpha)100\%$  quantile of  $N(0, 1)$  is a value  $z_\alpha$  such that

$$1 - \Phi(z_\alpha) = \alpha = \Phi(-z_\alpha)$$

where  $\Phi$  is the CDF of  $N(0, 1)$ .



- Two-sided z test: the level- $\alpha$  LRT for testing

$$H_0 : \mu = \mu_0 \text{ vs } H_1 : \mu \neq \mu_0$$



is

$$\psi(X_1, \dots, X_n) = 1\left(\frac{\sqrt{n}}{\sigma_0} |\bar{X} - \mu_0| \geq z_{\alpha/2}\right).$$

p-value:

$$2(1 - \Phi(|z_{obs}|))$$

where

$$z_{obs} = \frac{\sqrt{n}}{\sigma_0} (\bar{x} - \mu_0)$$

- One-sided z test: if instead, we wish to test

$$H_0 : \mu \leq \mu_0 \text{ vs } H_1 : \mu > \mu_0$$

Recall that the likelihood function  $L$  is increasing on  $(\infty, \bar{x}]$  and decreasing on  $[\bar{x}, \infty)$ . Hence,

$$\hat{\mu}_0 = \min(\bar{x}, \mu_0).$$

$$\psi(X_1, \dots, X_n) = 1\left(\frac{\sqrt{n}}{\sigma_0} (\bar{X} - \mu_0) \geq z_{\alpha}\right).$$

p-value

$$1 - \Phi(z_{obs})$$

- One-sided z test:

$$H_0 : \mu \geq \mu_0 \text{ vs } H_1 : \mu < \mu_0$$

$$\psi(X_1, \dots, X_n) = 1\left(\frac{\sqrt{n}}{\sigma_0} (\bar{X} - \mu_0) \leq -z_{\alpha}\right).$$

p-value

$$\Phi(z_{obs})$$

**Exmample 4.12** (T test).

Suppose that both  $\mu$  and  $\sigma^2$  are unknown. (Note that  $\sigma^2$  is a nuisance parameter.)

$$H_0 : \mu = \mu_0 \text{ vs } H_1 : \mu \neq \mu_0$$

The LRT has the form

$$\psi(X_1, \dots, X_n) = 1(\frac{\sqrt{n}}{S}|\bar{X} - \mu_0| \geq c^*)$$

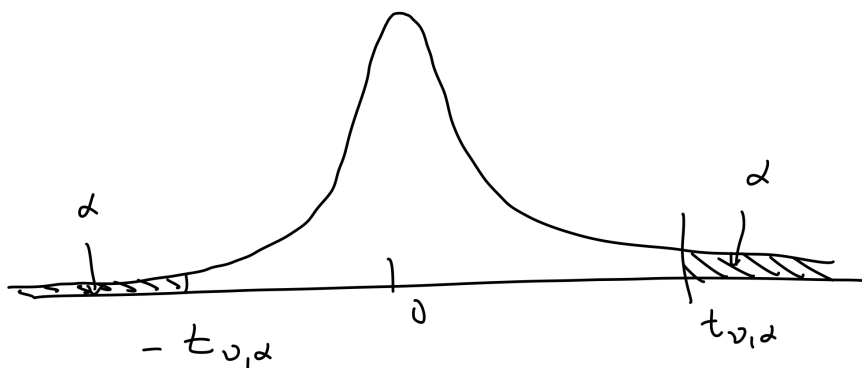
Recall from Theorem 1.26 that under  $H_0$ ,

$$\text{T statistic} = \frac{\sqrt{n}}{S}(\bar{X} - \mu_0) \sim t_{n-1}$$

**Definition 4.13**  $((1-\alpha)100\%$  quantile from the student t distribution) The  $(1-\alpha) \cdot 100\%$  quantile from the student t distribution with  $\nu$  dof is  $t_{\nu, \alpha}$  such that

$$P(T \geq t_{\nu, \alpha}) = \alpha$$

where  $T \sim t_{\nu}$ .



- Two-sided T-test:

$$\psi(X_1, \dots, X_n) = 1(\frac{\sqrt{n}}{S}|\bar{X} - \mu_0| \geq t_{n-1, \alpha/2})$$

$$p\text{-value} = P(|T| \geq |t_{obs}|)$$

$$t_{obs} = \frac{\sqrt{n}}{s}(\bar{x} - \mu_0)$$

$$T \sim t_{n-1}$$

- One-sided T-test:

$$H_0 : \mu \leq \mu_0 \text{ vs } H_1 : \mu > \mu_0$$

The level- $\alpha$  LRT is

$$\psi(X_1, \dots, X_n) = 1\left(\frac{\sqrt{n}}{S}(\bar{X} - \mu_0) \geq t_{n-1, \alpha}\right)$$

$$p\text{-value} = P(T \geq t_{obs})$$

- One-sided T-test:

$$H_0 : \mu \geq \mu_0 \text{ vs } H_1 : \mu < \mu_0$$

The level- $\alpha$  LRT is

$$\psi(X_1, \dots, X_n) = 1\left(\frac{\sqrt{n}}{S}(\bar{X} - \mu_0) \leq -t_{n-1, \alpha}\right)$$

$$p\text{-value} = P(T \leq t_{obs})$$

**Example 4.14** (F test). *Two independent random samples:*

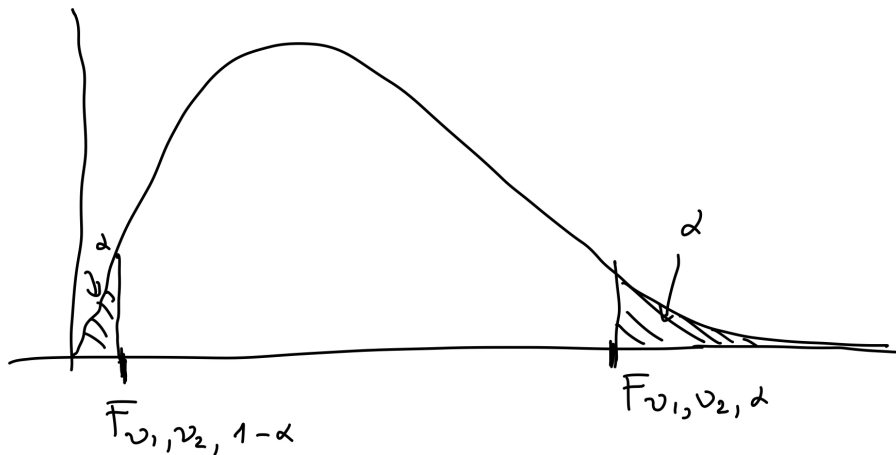
$$\underbrace{X_1, \dots, X_n}_{\text{random sample from } N(\mu_1, \sigma_1^2)} \quad \& \quad \underbrace{Y_1, \dots, Y_n}_{\text{random sample from } N(\mu_2, \sigma_2^2)}$$

$$H_0 : \sigma_1^2 = \sigma_2^2 \quad \text{vs} \quad H_1 : \sigma_1^2 \neq \sigma_2^2$$

**Definition 4.15.** *The  $(1 - \alpha) \cdot 100\%$  quantile of the  $F_{\nu_1, \nu_2}$  distribution is  $F_{\nu_1, \nu_2, \alpha}$  so that*

$$P(W \geq F_{\nu_1, \nu_2, \alpha}) = \alpha$$

where  $W \sim F_{\nu_1, \nu_2}$ .



The level- $\alpha$  LRT (F-test)

Assumptions:

- The samples are independent;
- The population distributions are normal for both samples.

$$\psi(X_1, \dots, X_m, Y_1, \dots, Y_n) = 1 \left( S_X^2/S_Y^2 \in (0, F_{m-1, n-1, 1-\alpha/2}] \cup [F_{m-1, n-1, \alpha/2}, \infty) \right)$$

p-values:  $W_{obs} = S_X^2/S_Y^2, W \sim F_{m-1, n-1}$

$$p\text{-value} = \begin{cases} 2P(W \geq w_{obs}), & w_{obs} > 1 \\ 2P(W \leq w_{obs}), & w_{obs} \leq 1 \end{cases}$$

**Remark 4.15** Other classical tests for normal samples that can be derived as LRTs:

(1) Chi-squared test:  $X_1, \dots, X_n$  random sample from  $N(\mu, \sigma^2)$

$$\begin{array}{l}
 H_0: \sigma^2 \leq \sigma_0^2 \quad \text{vs.} \quad H_1: \sigma^2 > \sigma_0^2 \\
 \psi = 1 \left( \frac{(n-1)S^2}{\sigma_0^2} \geq \chi_{n-1, \alpha}^2 \quad \left( \begin{array}{l} (1-\alpha) \cdot 100\% \\ \text{quantile of} \\ \chi_{n-1}^2 \end{array} \right) \right. \\
 \left. \leq \chi_{n-1, 1-\alpha}^2 \right) \\
 \sim \chi_{n-1}^2 \text{ when } \sigma^2 = \sigma_0^2 \quad \in \quad (0, \chi_{n-1, 1-\alpha/2}^2] \cup [\chi_{n-1, \alpha/2}^2, \infty)
 \end{array}$$

(2) Two-sample t test: Assumptions:

- The samples are independent;
- The population distributions are normal for both samples, with the same variance

(and possibly different means).  $X_1, \dots, X_m$  &  $Y_1, \dots, Y_n$

two independent samples;  $X_i \sim N(\mu, \sigma^2)$   
 $Y_i \sim N(\nu, \sigma^2)$

$H_0: \mu \leq \nu$  vs.  $H_1: \mu > \nu$   
 (Note:  $\leq$  and  $>$  are written with  $=$  and  $\neq$  below them respectively)

$$\psi = 1 \left( \frac{\sqrt{\frac{mn}{m+n}} (\bar{X} - \bar{Y})}{\sqrt{\frac{1}{m+n-2} ((m-1)S_X^2 + (n-1)S_Y^2)}} \right)$$

$\in (-\infty, -t_{n-2, \alpha}] \cup [t_{n-2, 1-\alpha}, \infty)$   
 $\sim t_{n-2}$  when  $\mu = \nu$

### 4.5 Uniformly most powerful tests

Recall the power of a test  $\psi$ :

$$B_\psi: \Theta \rightarrow [0, 1]$$

$$\theta \rightarrow B_\psi(\theta) = E_\theta \psi = P_\theta(X \in R)$$

So far, we were controlling the type 1 error (level- $\alpha$  test):

$$\sup_{\theta \in \Theta_0} B_\psi(\theta) \leq \alpha.$$

Now we can try to minimize the type 2 error, i.e. maximize  $B_\psi(\theta)$ ,  $\theta \in \Theta_1$ , but we cannot minimize both types of error at the same time.

**Definition 4.16** (UMP Test). A test  $\psi$  is called a uniformly most powerful (UMP) level- $\alpha$  test if its power satisfies

(a)

$$\sup_{\theta \in \Theta_0} B_\psi(\theta) \leq \alpha$$

(b) For any other level- $\alpha$  test  $\psi^*$  with  $B_{\psi^*}$ , we have that

$$\forall \theta \in \Theta_1 : B_{\psi}(\theta) \geq B_{\psi^*}(\theta)$$

(i.e.  $\psi$  minimizes the type 2 error uniformly over  $\Theta_1$ )

**Definition 4.17.**  $H_i$ ,  $i \in \{0, 1\}$  is called simple if  $\Theta_i$  is a singleton, i.e.  $|\Theta_i| = 1$ . Otherwise,  $H_i$  is called composite.

We will start developing a theory for finding UMP tests. We will begin by considering the case of testing a simple  $H_0$  vs a simple  $H_1$ .

•

$$\Theta = \{\theta_0, \theta_1\}$$

•  $H_0 : \theta = \theta_0$  vs  $H_1 : \theta = \theta_1$

• KNAPSACK Problem

**Theorem 4.18** (Neyman-Pearson Lemma). Consider  $\Theta = \{\theta_0, \theta_1\}$ ,  $H_0 : \theta = \theta_0$  vs  $H_1 : \theta = \theta_1$ . Suppose that

$$f(x_1, \dots, x_n; \theta_i), \quad i \in \{0, 1\}$$

is the PDF/PMF of  $(X_1, \dots, X_n)$  when  $\theta = \theta_i$ . Define the so-called NP test  $\psi_k$ ,  $k \in [0, \infty]$ :

$$\psi_k(x_1, \dots, x_n) = \begin{cases} 1, & f(x_1, \dots, x_n; \theta_1) \geq k \cdot f(x_1, \dots, x_n; \theta_0) \\ 0, & f(x_1, \dots, x_n; \theta_1) < k \cdot f(x_1, \dots, x_n; \theta_0) \end{cases}$$

Then  $\psi_k$  is a UMP test for  $H_0$  vs  $H_1$  at level

$$\alpha = P_{\theta_0}(\psi_k(X_1, \dots, X_n) = 1).$$

**Remark 4.19.** If  $\psi_k$  is randomized test:

$$\psi_k(\tilde{x}) = \begin{cases} 1, & f(\tilde{x}; \theta_1) > k \cdot f(\tilde{x}; \theta_0) \\ \gamma, & f(\tilde{x}; \theta_1) = k \cdot f(\tilde{x}; \theta_0) \\ 0, & f(\tilde{x}; \theta_1) < k \cdot f(\tilde{x}; \theta_0) \end{cases}$$

**Example 4.20.**  $X_1, \dots, X_n$  from  $N(\mu, \sigma_0^2)$ ,  $\sigma_0^2$  is assumed to be known, so the parameter space is  $\mathbb{R}$ . Consider testing:

$$H_0 : \mu \leq \mu_0 \text{ vs } H_1 : \mu > \mu_0$$

Fix an arbitrary  $\mu_1 > \mu_0$ . Consider testing the auxiliary problem:

$$H_0^* : \mu = \mu_0 \text{ vs } H_1^* : \mu = \mu_1$$

If we simply set  $k^* = z_\alpha$ ,

$$\begin{aligned} \psi_{NP}(X_1, \dots, X_n) &= 1\left(\frac{\sqrt{n}}{\sigma_0}(\bar{X} - \mu_0) \geq z_\alpha\right) \\ &= \psi_z(X_1, \dots, X_n) \end{aligned}$$

which is a one-sided  $z$  test. Note that the test  $\psi_{NP}$  has nothing to do with  $\mu_1$ . Hence,  $\psi_z$  is UMP for  $H_0 : \mu = \mu_0$  vs  $H_1 : \mu > \mu_0$ .

**Definition 4.21.** A family

$$P = \{P_\theta : \theta \in \Theta \subset \mathbb{R}\}$$

of distribution with PMF/PDF  $f(\cdot; \theta)$ ,  $\theta \in \Theta$  is said to have a monotone likelihood ratio (MLR) is a statistic  $T : \chi \rightarrow \mathbb{R}$  if

(1)

$$\Theta \rightarrow P$$

$$\theta \rightarrow P_\theta$$

is injective.



(2) For every  $\theta_1, \theta_2 \in \Theta$ ,  $\theta_1 < \theta_2$ , there exists version of  $f(\cdot; \theta_1)$   $f(\cdot; \theta_2)$  and a non-decreasing mapping  $h(\cdot; \theta_1, \theta_2) : \mathbb{R} \rightarrow \mathbb{R} \cup \{\infty\}$  so that

$$\frac{f(\tilde{x}; \theta_2)}{f(\tilde{x}; \theta_1)} = h(T(\tilde{x}); \theta_1, \theta_2)$$

on the set  $\{x \in \mathcal{X} : f(\tilde{x}; \theta_1) > 0 \text{ or } f(\tilde{x}; \theta_2) > 0\}$ ; here " $\frac{a}{\infty} = 0$ " if  $a > 0$ .

**Example 4.22.** In the setup of Example 4.20,,

$$P = \{P_\mu, \mu \in \mathbb{R}\}$$

has a MLR in  $T = \bar{X}$ .

**Theorem 4.23** (Karlin-Rubin). Let  $X_1, \dots, X_n$  be a random sample and  $P$  the family of distribution of  $(X_1, \dots, X_n)$ . Suppose

$$P = \{P_\theta, \theta \in \Theta \subset \mathbb{R}\},$$

and  $P$  has a MLR in a statistic  $T$ .

$$H_0 : \theta \leq \theta_0 \quad \text{vs.} \quad H_1 : \theta > \theta_0$$

let  $\alpha \in (0, 1)$  and  $\psi_{KR}$  be a test given by

$$\psi_{KR}(\tilde{x}) = \begin{cases} 1 & \text{if } T(\tilde{x}) > k \\ \gamma & \text{if } T(\tilde{x}) = k \\ 0 & \text{if } T(\tilde{x}) < k \end{cases}$$

where  $\gamma$  and  $k$  are such that

$$(*) \quad P_{\theta_0}(T > k) + \gamma \cdot P_{\theta_0}(T = k) = \alpha$$

Then :

- (1)  $\psi_{KR}$  minimizes uniformly the type 2 and type 1 error among all tests  $\psi$  with  $E_{\theta_0}\psi = \alpha$ .
- (2)  $\psi_{KR}$  is a UMP level  $\alpha$  test for  $H_0$  vs  $H_1$
- (3)  $B_{\psi_{KR}}$  is non-decreasing (non-increasing) in  $\theta$ .

**Remark 4.24.** Let  $F_{\theta}^T$  denote the CDF of  $T$ , i.e.  $F_{\theta}^T(t) = P_{\theta}(T \leq t)$ ,

$$(F_{\theta}^T)^{-1}(u) = \inf\{x : F_{\theta}^T(x) \geq u\}, \quad u \in (0, 1).$$

Then: for

$$H_0: \theta \leq \theta_0 \quad \text{vs.} \quad H_1: \theta > \theta_0$$

We can set

$$k = (F_{\theta_0}^T)^{-1}(1 - \alpha)$$

$$\gamma = \begin{cases} \frac{\alpha - P_{\theta_0}(T > k)}{P_{\theta_0}(T = k)}, & \text{if } P_{\theta_0}(T = k) \neq 0 \\ 1, & \text{if } P_{\theta_0}(T = k) = 0 \end{cases}$$

**Example 4.25.**  $X_1, \dots, X_n$  random sample from  $Poisson(\lambda)$ ,  $\lambda > 0$ .  $P$  has a MLR in  $T = \sum_{i=1}^n X_i$ .

The UMP test for testing

$$H_0: \lambda \leq \lambda_0 \text{ vs. } H_1: \lambda > \lambda_0$$

is

$$\psi(x_1, \dots, x_n) = \begin{cases} 1 & \sum_{i=1}^n x_i > k \\ \gamma & \sum_{i=1}^n x_i = k \\ 0 & \sum_{i=1}^n x_i < k \end{cases}$$

For example, when  $\alpha = 0.05$ ,  $n = 10$ ,  $\lambda_0 = 5$ ,

$$\begin{aligned} k &= \left( F_{\lambda_0}^T \right)^{-1} (0.95) = qpois(0.95, 50) \\ &= 62. \\ \uparrow &= \frac{0.05 - P(W > 62)}{P(W = 62)} = \frac{0.05 - 1 + ppois(62, 50)}{dpois(62, 50)} \\ &= 0.573 \end{aligned}$$

Note: if  $X \sim \text{Poisson}(\lambda_1)$  and  $Y \sim \text{Poisson}(\lambda_2)$  and  $X$  and  $Y$  are independent, then  $X + Y \sim \text{Poisson}(\lambda_1 + \lambda_2)$ .

**Example 4.26.** Consider the setup of Example 4.20. We wish to test

$$H_0: \mu = \mu_0 \text{ vs } H_1: \mu \neq \mu_0$$

A UMP level- $\alpha$  test  $\psi$  would need to satisfy

•

$$E_{\mu_0} \psi \leq \alpha$$

•

$$E_{\mu} \psi = \sup \{ E_{\mu} \psi^* : \psi^* \text{ is a test such that } E_{\theta_0} \psi^* \leq \alpha \}$$

Now for all  $\mu > \mu_0$  :  $\psi$  would be UMP for

$$H_0 : \mu = \mu_0 \text{ vs } H_1^* : \mu > \mu_0$$

for all  $\mu < \mu_0$  :  $\psi$  would be UMP for

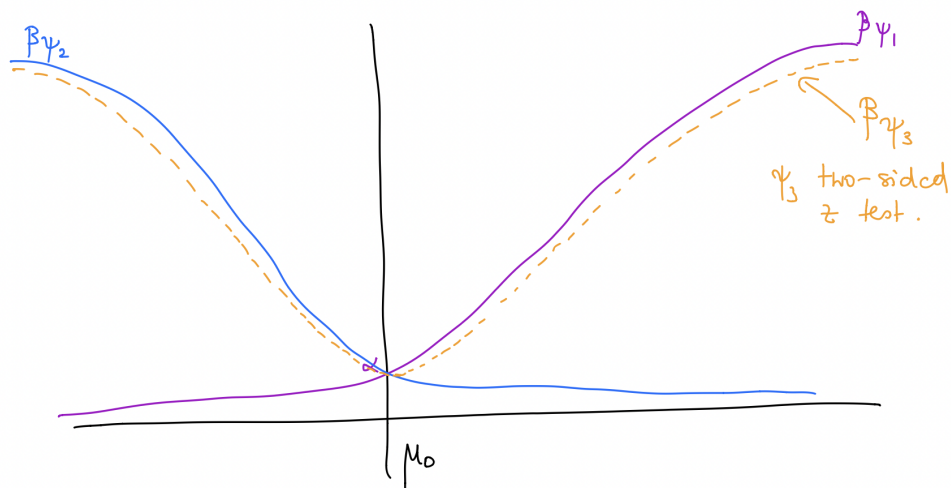
$$H_0 : \mu = \mu_0 \text{ vs } H_1^{**} : \mu < \mu_0$$

$$\begin{aligned} \psi = \psi_1 &= 1\left(\frac{\sqrt{n}}{\sigma_0}(\bar{X} - \mu_0) \geq z_\alpha\right) \\ &= \psi_2 = 1\left(\frac{\sqrt{n}}{\sigma_0}(\bar{X} - \mu_0) \leq -z_\alpha\right) \end{aligned}$$

But

$$\{x : \psi_1 \neq \psi_2\} = \{x : \frac{\sqrt{n}}{\sigma_0}(\bar{x} - \mu_0) \geq z_\alpha \text{ or } \frac{\sqrt{n}}{\sigma_0}(\bar{x} - \mu_0) \leq -z_\alpha\}$$

does not have probability 0. So such a test  $\psi$  does not exist.



Convention: we can develop a theory of UMP level- $\alpha$  tests for the two-sided theory problems. ( $\theta = \theta_0$  vs  $\theta \neq \theta_0$ ) if we restrict attention to unbiased tests:

$$B_\psi(\theta) \geq \alpha \quad \forall \theta \neq \theta_0$$

## 5 Chapter 5: Confidence Sets

### 5.1 Confidence set

Goal: express uncertainty in parametric estimates

**Definition 5.1** (Confidence set). *Consider a parametric model*

$$P = \{P_{\theta, \xi}, (\theta, \xi) \in \mathfrak{L}\}.$$

Here,  $\theta$  is the parameter of interest and  $\xi$  is a nuisance parameter. Let  $\Theta = \{\theta : (\theta, \xi) \in \mathfrak{L}, \text{ for at least one } \xi\}$ . The mapping

$$\begin{aligned} C : \mathcal{X} &\rightarrow 2^\Theta \\ (x_1, \dots, x_n) &\rightarrow c(x) \end{aligned}$$

is called a confidence set for  $\theta$  if for all  $\theta \in \Theta$  the set  $\{x \in \mathcal{X} : \theta \in c(x)\}$  is measurable.

A confidence set  $c$  has confidence level  $1 - \alpha$  if  $\forall \theta \in \Theta, \forall \xi : (\theta, \xi) \in \mathfrak{L}$

$$P_{\theta, \xi}(\theta \in C(\tilde{X})) \geq 1 - \alpha$$

**Remark** If there are no nuisance parameters,  $\xi$  is simply omitted in Def 5.1 and  $\mathfrak{L} = \Theta$ .

**Example 5.2** (Constructing confidence sets using pivots).  $X_1, \dots, X_n$  random sample from the Exponential distribution with density

$$f(x; \lambda) = \lambda e^{-\lambda x}, \quad x > 0$$

$$P = \{Exp(\lambda), \lambda \in (0, \infty)\}$$

Goal: construct CS for  $\lambda$ .

Note:

$$\sum_{i=1}^n X_i \sim \text{Gamma}(n, \lambda)$$

Define

$$Q = 2\left(\sum_{i=1}^n X_i\right) \cdot \lambda = Q(\tilde{X}, \lambda) \sim \chi_{2n}^2 \text{ does not depend on } \lambda$$

The MGF of  $Q$  is

$$\begin{aligned} E_{\lambda} \left( e^{tQ} \right) &= E_{\lambda} \left( e^{(2t\lambda) \sum_{i=1}^n X_i} \right) = \left( E_{\lambda} e^{(2t\lambda)X_i} \right)^n \\ &= \left( 1 - \frac{2t\lambda}{\lambda} \right)^{-n} = \boxed{(1-2t)^{-n}, t < \frac{1}{2}.} \\ &\quad \text{MGF } \chi_{2n}^2 \end{aligned}$$

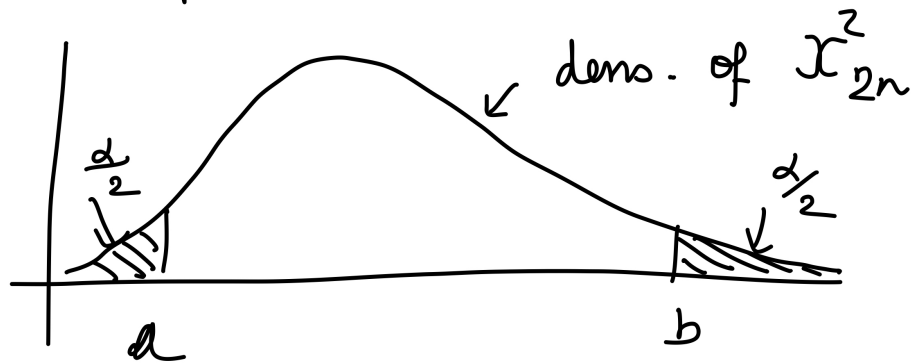
$$\Rightarrow Q = Q(\tilde{X}, \lambda) \sim \chi_{2n}^2 = \text{does not depend on } \lambda.$$

A quantity which depends on  $(X_1, \dots, X_n)$  and the parameter of interest  $\theta$ , and whose distribution does not depend on  $\theta$  or  $\xi$  is called a **PIVOT**.

To construct a confidence set for  $\lambda$  from  $Q$ , we can simply choose  $(a, b)$  so that the CS is at confidence level  $1 - \alpha$ . Here, we choose  $a, b \in \mathbb{R}$ ,  $a < b$ , so that

$$P(\chi_{2n}^2 \in (a, b)) = 1 - \alpha.$$

For example, we can set  $a = \chi_{2n, 1-\alpha/2}^2$ ,  $b = \chi_{2n, \alpha/2}^2$



To obtain the CS from  $(a, b)$ , we can solve for

$$a < Q(\tilde{X}, \lambda) < b$$

$$\frac{a}{2 \sum_{i=1}^n X_i} < \lambda < \frac{b}{2 \sum_{i=1}^n X_i}$$

Set

$$C(\tilde{X}) = \left( \frac{a}{2 \sum_{i=1}^n X_i}, \frac{b}{2 \sum_{i=1}^n X_i} \right)$$

Then, for any  $\lambda > 0$ ,

$$\begin{aligned} & P_\lambda \left( \lambda \in \left( \frac{a}{2 \sum_{i=1}^n X_i}, \frac{b}{2 \sum_{i=1}^n X_i} \right) \right) \\ &= P_\lambda \left( a < 2 \left( \sum_{i=1}^n X_i \right) < b \right) \\ &= P(\chi_{2n}^2 \in (a, b)) = 1 - \alpha \end{aligned}$$

Hence,  $C(\tilde{X})$  above is a confidence set for  $\lambda$  at confidence level  $1 - \alpha$ .

**Example 5.3** (More Pivots).  $X_1, \dots, X_n$  a random sample from  $N(\mu, \sigma^2)$ . We wish to construct a confidence set at level  $(1 - \alpha)$  for  $\mu$  (i.e.  $\sigma^2$  is a nuisance parameter). Define

$$Q(X_1, \dots, X_n, \mu) = \frac{\sqrt{n}(\bar{X} - \mu)}{S} \sim t_{n-1}$$

Choose  $(a, b)$ , i.e.,  $a, b \in \mathbb{R}$  so that

$$P(t_{n-1} \in (a, b)) = 1 - \alpha$$

**Definition 5.4.** Suppose that  $C(\tilde{X})$  is confidence set for  $\theta$  at level  $1 - \alpha$ .

- If  $C(\tilde{X})$  has the form  $(L(\tilde{X}), U(\tilde{X}))$ , then  $C$  is called a two-sided confidence interval at confidence level  $1 - \alpha$ .
- If  $C(\tilde{X})$  has the form  $(\infty, U(\tilde{X}))$ , then  $C$  is called upper one-sided confidence interval at confidence level  $1 - \alpha$ .
- If  $C(\tilde{X})$  has the form  $(L(\tilde{X}), \infty)$ , then  $C$  is called lower one-sided confidence interval at confidence level  $1 - \alpha$ .

**Definition 5.5** (Unbiased confidence set). For any  $\theta \in \Theta$ , let  $k_\theta$  be a set of undesirable parameters. A confidence set at confidence level  $1 - \alpha$  is called unbiased if

$$\forall \theta \in \Theta, \forall \xi : (\theta, \xi) \in \mathcal{L}, \forall \theta^* \in k_\theta, P_{\theta, \xi}(\theta^* \in C(\tilde{X})) \leq 1 - \alpha$$

**Example 5.6** (Ex 5.3 continued).  $X_1, \dots, X_n$  sample from  $N(\mu, \sigma^2)$ ,  $\mu$  of interest,  $\sigma^2$  nuisance,  $k_\mu = (\infty, \mu)$ . For  $\mu^* \in k_\mu$ ,

$$\begin{aligned} & P_{\mu, \sigma^2}(\mu^* \in (\bar{X} - \frac{t_{n-1, \alpha} \cdot S}{\sqrt{n}}, \infty)) \\ &= P_{\mu, \sigma^2}(\frac{\bar{X} - \mu}{S} \sqrt{n} < t_{n-1, \alpha} + \underbrace{\frac{\mu^* - \mu}{S} \sqrt{n}}_{< 0}) \\ &\leq P_{\mu, \sigma^2} \left( \underbrace{\frac{\bar{X} - \mu}{S} \cdot \sqrt{n}}_{\sim t_{n-1}} < t_{n-1, \alpha} \right) = 1 - \alpha. \end{aligned}$$

- Similarly, if  $k_\mu = (\mu, \infty)$

$$(-\infty, \bar{X} + \frac{t_{n-1, \alpha} \cdot S}{\sqrt{n}})$$

is unbiased



- Similarly, if  $k_\mu = \{\mu\}^C$

$$\left(\bar{X} - \frac{t_{n-1,\alpha} \cdot S}{\sqrt{n}}, \bar{X} + \frac{t_{n-1,\alpha} \cdot S}{\sqrt{n}}\right)$$

is unbiased.

## 5.2 Correspondence between confidence sets and hypothesis tests

**Theorem 5.7.** For any confidence set  $C$ , there exists a family of non-randomized tests

$$\{\psi_{\theta_0}, \theta_0 \in \Theta\}$$

with

$$C(\tilde{x}) = \{\theta_0 \in \Theta : \psi_{\theta_0}(\tilde{x}) = 0\}$$

is measurable for all  $\theta_0$  since  $\theta_0$  is measurable.

**Example 5.8.**  $X_1, \dots, X_n$  random sample from  $N(\mu, \sigma^2)$ . In Example 5.3, we derived CI for  $\mu$  using pivots.

- lower one-sided confidence interval for  $\mu$ :

$$\left(\bar{X} - \frac{t_{n-1,\alpha} \cdot S}{\sqrt{n}}, \infty\right)$$

we can calculate, for  $\mu_0 \in \mathbb{R}$ ,

$$\begin{aligned} \psi_{\mu_0}(\tilde{x}) &= \begin{cases} 1, & \mu_0 \notin \left(\bar{X} - \frac{t_{n-1,\alpha} \cdot S}{\sqrt{n}}, \infty\right) \\ 0, & \mu_0 \in \left(\bar{X} - \frac{t_{n-1,\alpha} \cdot S}{\sqrt{n}}, \infty\right) \end{cases} \\ &= \begin{cases} 1, & \mu_0 \leq \bar{X} - \frac{t_{n-1,\alpha} \cdot S}{\sqrt{n}} \\ 0, & \mu_0 > \bar{X} - \frac{t_{n-1,\alpha} \cdot S}{\sqrt{n}} \end{cases} \\ &= \begin{cases} 1, & \frac{\bar{X} - \mu_0}{S} \cdot \sqrt{n} \geq t_{n-1,\alpha} \\ 0, & \frac{\bar{X} - \mu_0}{S} \cdot \sqrt{n} < t_{n-1,\alpha} \end{cases} \end{aligned}$$

This is the one-sided  $t$ -test (Ex 4.12) for

$$H_0 : \mu \leq \mu_0 \text{ vs } H_1 : \mu > \mu_0$$

- For the two-sided confidence interval for  $\mu$ :

$$\left( \bar{X} - \frac{t_{n-1, \alpha} \cdot S}{\sqrt{n}}, \bar{X} + \frac{t_{n-1, \alpha} \cdot S}{\sqrt{n}} \right)$$

we can derive the associated family of tests. For any  $\mu_0 \in \mathbb{R}$ ,

$$\begin{aligned} \psi_{\mu_0} &= \begin{cases} 1, & \mu \notin \left( \bar{x} - \frac{t_{n-1, \alpha/2} \cdot S}{\sqrt{n}}, \bar{x} + \frac{t_{n-1, \alpha/2} \cdot S}{\sqrt{n}} \right) \\ 0, & \mu \in \left( \bar{x} - \frac{t_{n-1, \alpha/2} \cdot S}{\sqrt{n}}, \bar{x} + \frac{t_{n-1, \alpha/2} \cdot S}{\sqrt{n}} \right) \end{cases} \\ &= \begin{cases} 1, & \sqrt{n} \left| \frac{\bar{x} - \mu_0}{s} \right| \geq t_{n-1, \frac{\alpha}{2}} \\ 0, & \sqrt{n} \left| \frac{\bar{x} - \mu_0}{s} \right| < t_{n-1, \frac{\alpha}{2}} \end{cases} \end{aligned}$$

This is the two-sided  $t$  test for

$$H_0 : \mu = \mu_0 \text{ vs } H_1 : \mu \neq \mu_0.$$

**Theorem 5.9.** Consider a confidence set  $C$  and the corresponding family of tests  $\{\psi_{\theta_0}, \theta_0 \in \Theta\}$  as specified in Theorem 5.7. Let also, for any  $\theta \in \Theta$ ,  $k_\theta$  be the set of undesirable parameters. For each  $\theta_0 \in \Theta$ , let

$$\Theta_1^{\theta_0} = \{\theta \in \Theta : \theta_0 \in k_\theta\}$$

Then the following holds:

- (1)  $C$  has confidence level  $1 - \alpha$  if and only if  $\forall (\theta_0, \xi) \in \mathcal{L}$  :

$$E_{(\theta_0, \xi)} \psi_{\theta_0}(\tilde{X}) \leq \alpha$$

- (2)  $C$  is an unbiased level- $(1 - \alpha)$  confidence set for  $\theta$  if and only if, for each  $\theta_0 \in \Theta$ ,  $\psi_{\theta_0}$  is an **unbiased** level- $\alpha$  test of

$$H_0 : \theta = \theta_0 \text{ vs } H_1 : \theta \in \Theta_1^{\theta_0}$$

Note that Theorem 5.9 only guarantees the null hypothesis that  $\theta = \theta_0$ . **unbiased** means type 2 error  $\leq 1 - \alpha$ .

**Example 5.10.** From 5.6, we know that if  $k_\mu = (-\infty, \mu)$ , then

$$\left( \bar{X} - \frac{t_{n-1, \alpha} \cdot S}{\sqrt{n}}, \infty \right)$$

is an unbiased level- $(1 - \alpha)$  CI for  $\mu$ . For  $\mu_0 \in \mathbb{R}$ :

$$\{\mu \in \mathbb{R} : \mu_0 \in (-\infty, \mu)\} = (\mu_0, \infty).$$

Hence, from Theorem 5.9, the one-sided  $t$ -test

$$\psi_{\mu_0} = \begin{cases} 1, & \sqrt{n} \frac{\bar{X} - \mu_0}{S} \geq t_{n-1, \alpha} \\ 0, & \sqrt{n} \frac{\bar{X} - \mu_0}{S} < t_{n-1, \alpha} \end{cases}$$

is unbiased, level- $\alpha$  test for

$$H_0 : \mu = \mu_0 \text{ vs } H_1 : \mu > \mu_0$$

•  $K_\mu = \{\mu\}^c \rightarrow$  two-sided CI for  $\mu$ .

$$\left( \bar{X} - \frac{t_{n-1, \frac{\alpha}{2}} \cdot S}{\sqrt{n}}, \bar{X} + \frac{t_{n-1, \frac{\alpha}{2}} \cdot S}{\sqrt{n}} \right)$$

(unbiased, level- $(1 - \alpha)$ )

$$\{\mu \in \mathbb{R} : \mu_0 \in \{\mu\}^c\} = \{\mu \in \mathbb{R} : \mu \neq \mu_0\}$$

Two-sided  $t$ -test is an unbiased, level- $\alpha$  test for  $H_0 : \mu = \mu_0$  vs.  $H_1 : \mu \neq \mu_0$ .

**Example 5.11** (Constructing CS from tests).  $X_1, \dots, X_n$  random sample from  $N(\mu, \sigma^2)$ ,  $\mu$  nuisance; our goal is to construct confidence sets for  $\sigma^2$ .

Recall chi-square test

Remark 4.15 :

$$H_0 : \sigma^2 \leq \sigma_0^2 \quad \text{vs.} \quad H_1 : \sigma^2 > \sigma_0^2$$

$$\Psi_{\sigma_0^2}(\tilde{x}) = 1 \left( \frac{(n-1)S^2}{\sigma_0^2} \right)$$

$\in (0, \chi_{n-1, 1-\alpha}^2] \cup [\chi_{n-1, \alpha/2}^2, \infty)$

•

$$k_{\sigma^2} = (0, \sigma^2) \rightarrow H_1 : \sigma_0^2 < \sigma^2$$

$$C(\tilde{x}) = \left( \frac{(n-1)S^2}{\chi_{n-1, \alpha}^2}, \infty \right)$$

•

$$k_{\sigma^2} = \{\sigma^2\}^C \rightarrow H_1 : \sigma_0^2 \neq \sigma^2$$

$$C(\tilde{x}) = \left( \frac{(n-1)S^2}{\chi_{n-1, \alpha/2}^2}, \frac{(n-1)S^2}{\chi_{n-1, 1-\alpha/2}^2} \right)$$

**Remark 5.12.** The correspondence between the tests and CS can also be used to develop uniformly most accurate CSs (these correspond to UMP classes of tests.)

### 5.3 Interpretation of Confidence Sets

**Example 5.13.** Generate a sample of size  $n = 10$  from  $N(1, 2)$ . Suppose for this sample, we observed

$$\bar{x} = 1.1, \quad s^2 = 1.5$$

two-sided CI for  $\mu$  at CL  $95\%$ :

$$\left( \bar{x} - \frac{t_{9, 0.025} \cdot \sqrt{1.5}}{\sqrt{10}}, \bar{x} + \frac{\quad \quad \quad}{\quad \quad \quad} \right)$$

2.262

$\Rightarrow (0.224, 1.976)$ .

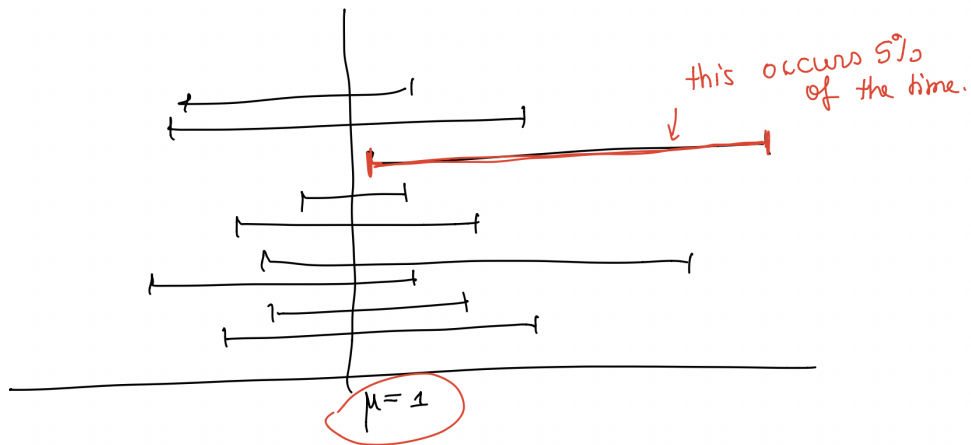
Test:  $\mu = 1$  vs.  $\mu \neq 1$ .

Since  $1 \in (0.224, 1.976) \Rightarrow$  do not reject at the  $5\%$  level

• Interpreting  $(0.224, 1.976)$ ?

"This is the interval in which the true  $\mu$  lies with probability 95%"

No!



• set of "plausible values of  $\mu$ "